# Time Consistency and Calculation of Risk Measures in Markets with Transaction Costs

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- Oynamic set-valued risk measures
- **2** Time consistency
- **③** Examples and calculation of risk measures
  - Superhedging under transaction costsAV@R
- 4 Multi-portfolio time consistency by composition

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$$X+u \in A_t$$

for some set  $A_t \subseteq L^p_d(\mathcal{F}_T)$  of acceptable positions.

 $M_t \subseteq L^p_d(\mathcal{F}_t) \qquad (M_t)_+ = M_t \cap L^p_d(\mathcal{F}_t)_+$ 

Conditional Set-Valued Risk Measure

B. Rudloff

Dynamic risk measures in markets with transaction costs

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#### Conditional Set-Valued Risk Measure

A set-valued function  $R_t: L^p_d(\mathcal{F}_T) \to \mathcal{P}((M_t)_+) = \{D \subseteq M_t: D = D + (M_t)_+\}$  is a conditional risk measure if

• Finite at zero:  $\emptyset \neq R_t(0) \neq M_t$ 

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- Finite at zero:  $\emptyset \neq R_t(0) \neq M_t$
- **2**  $M_t$  translative:  $R_t(X+m) = R_t(X) m$  for any  $m \in M_t$

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  - A conditional risk measure is **normalized** if for any  $X \in L^p_d(\mathcal{F}_T)$ :  $R_t(X) + R_t(0) = R_t(X)$

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  - dynamic risk measure: sequence  $(R_t)_{t=0}^T$  of conditional risk measures

#### Primal Representation

Risk measures and acceptance sets are one-to-one via

$$R_t(X) = \{ u \in M_t : X + u \in A_t \}$$

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	$R_t$	$A_t$
finite at zero	$\emptyset \neq R_t(0) \neq M_t$	$M_t \mathbb{1} \cap A_t \neq \emptyset$ $M_t \mathbb{1} \cap (L^p_d \backslash A_t) \neq \emptyset$
monotone	$Y - X \in L^p_d(\mathcal{F}_T)_+ \Rightarrow R_t(Y) \supseteq R_t(X)$	$A_t + L^p_d(\mathcal{F}_T)_+ \subseteq A_t$
	convex	convex
	positively homogeneous	cone
	subadditive	$A_t + A_t \subseteq A_t$
	closed images	directionally closed
	lsc	closed
market compatible	$R_t(X) = R_t(X) + K_t^{M_t}$	$A_t + L^p_d(K^{M_t}_t) \subseteq A_t$

Let 
$$\mathcal{G}((M_t)_+) = \{ D \subseteq M_t : D = \operatorname{cl}\operatorname{co}(D + (M_t)_+) \}.$$

#### Dual Representation, $1 \le p \le \infty$

A function  $R_t : L^p_d(\mathcal{F}_T) \to \mathcal{G}((M_t)_+)$  is a closed **coherent conditional risk measure** if and only if there is a nonempty set  $\mathcal{W}^q_{t,R_t} \subseteq \mathcal{W}^q_t$  such that

$$R_t(X) = \bigcap_{(\mathbb{Q},w)\in\mathcal{W}_{t,R_t}^q} \{E_t^{\mathbb{Q}}[-X] + G_t(w)\} \cap M_t.$$

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G<sub>t</sub>(w) = {v ∈ L<sup>p</sup><sub>d</sub>(F<sub>t</sub>) : E[w<sup>T</sup>v] ≥ 0}.

$$\mathcal{W}_{t}^{q} = \left\{ (\mathbb{Q}, w) \in \mathcal{M}_{1,d}^{\mathbb{P}} \times \left( \left( (M_{t})_{+} \right)^{+} \setminus (M_{t})^{\perp} \right) : \\ \operatorname{diag}(w) \operatorname{diag}\left( E_{t} \left[ \frac{d\mathbb{Q}}{d\mathbb{P}} \right] \right)^{-1} \frac{d\mathbb{Q}}{d\mathbb{P}} \in L_{d}^{p}(\mathcal{F}_{T})_{+} \right\}.$$

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analog for convex set-valued risk measures

static set-valued risk measures: ▷ JOUINI, TOUZI, MEDDEB (2004), HAMEL, RUDLOFF (2008), HAMEL, HEYDE (2010), HAMEL, HEYDE, RUDLOFF (2011)

# **Time Consistency**

B. Rudloff

Dynamic risk measures in markets with transaction costs

### 2. Time Consistency: Background

Time Consistency: scalar case

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$$A_t = A_{t,t+1} + A_{t+1}$$
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In the scalar case  $R_t(X) = \{u \in L^p(\mathcal{F}_t) : \rho_t(X) \leq u\} : (\rho_t)_{t=0}^T$ time consistent iff multi-portfolio time consistent. In higher dimensions: multi-portfolio time consistency implies time consistency.

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 where  $A_{t,t+1}^{M_{t+1}} = A_t \cap M_{t+1}$ 

# Examples

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Dynamic risk measures in markets with transaction costs

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•  $(V_t)_{t=0}^T$  self-financing portfolio process if

 $V_t - V_{t-1} \in -K_t \quad P - a.s. \quad \forall t \in \{0, ..., T\} \quad (V_{-1} \equiv 0)$ 

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•  $L^p_d(\mathcal{F}_T)$ -attainable claims (from zero cost at time t)

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Set of superhedging portfolios for  $X \in L^p_d(\mathcal{F}_T)$ 

$$SHP_t(X) := \{ u \in L^p_d(\mathcal{F}_t) : -X + u \in -C_{t,T} \}.$$

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Set of superhedging portfolios for  $X \in L^p_d(\mathcal{F}_T)$ 

$$SHP_t(X) := \{ u \in L^p_d(\mathcal{F}_t) : -X + u \in -C_{t,T} \}.$$

Under robust no arbitrage condition (NA<sup>r</sup>):  $R_t(X) := SHP_t(-X)$  is a closed market-compatible **coherent dynamic risk measure** on  $L^p_d(\mathcal{F}_T)$  that is **multi-portfolio time consistent**.

B. Rudloff

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Dynamic risk measures in markets with transaction costs

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LOEHNE, RUDLOFF 12 (SUBMITTED), HAMEL, LOEHNE, RUDLOFF 12 (WORKING PAPER)

## **European Call Option**

Asset 0: riskless bond, r = 10%, no transaction cost

Asset 1: stock, CRR, constant transaction cost  $\lambda=0.125\%$ 

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$\lambda = 0.125\%$ for all t			
n	6	250	1800
vert $SubHP_0(X)$	$\left(\begin{array}{c} -74.434\\ 0.953\end{array}\right)$	$\left(\begin{array}{c} -76.348\\ 0.969\end{array}\right)$	$\left(\begin{array}{c} -79.049\\ 0.992 \end{array}\right)$
$\pi^b(X)$	27.552	27.381	27.191
vert $SHP_0(X)$	$\left(\begin{array}{c} -73.814\\ 0.948\end{array}\right)$	$\left(\begin{array}{c} -72.856\\ 0.941 \end{array}\right)$	$\left(\begin{array}{c} -70.209\\ 0.921 \end{array}\right)$
$\pi^{a}(X)$	27.854	27.994	28.370
$\lambda = 0.125\%$ for $t = 1,, T$ , but no transaction cost at $t = 0$			
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Note: small intervals despite Kusuoka (95) result!

## Multiple vertices

 $-SHP_0(-X), \lambda = 2\%, K = 110, n = 52$ : 8 vertices

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 $-SHP_0(-X), \lambda = 2\%, K = 110, n = 250: 3$  vertices

(	2.370	-107.125	-110.107	
$\left( \right)$	-0.036	0.973	1.001	)

Tree approximating (d-1)-dim Black-Scholes-Model by Korn, Müller (09)

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# Example: Exchange Option

physical delivery

$$X = (X_1, X_2, X_3)^T$$
  
=  $\left(0, I_{\left\{S_T^{a,1} \ge S_T^{a,2}\right\}}, -I_{\left\{S_T^{a,1} \ge S_T^{a,2}\right\}}\right)^T$ .

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(cash delivery:  $X = ((S_T^1 - S_T^2)^+, 0, 0)^T)$ 

## Exchange Option, n = 4, includes transaction costs for bond

$r = 5\%, \ \lambda = (1\%, 2\%, 4\%)^T$ vertex of $SHP_0(X)$	$\left(\begin{array}{cccc} 13.341 & 0.000 & -7.760 \\ 0.347 & 0.498 & 0.584 \\ -0.446 & -0.331 & -0.260 \end{array}\right)$
$ \begin{aligned} \pi^a_0(X) & \text{(in bonds)} \\ \pi^a(X) & \text{(in cash)} \end{aligned} $	$7.418 \\ 6.988$
$r = 5\%, \ \lambda = (0.2\%, 0.4\%, 0.1\%)^T$ vertex of $SHP_0(X)$	$\left(\begin{array}{cccccc} 12.403 & 8.230 & 0.000 & -6.236 & -4.237 \\ 0.308 & 0.353 & 0.441 & 0.507 & 0.486 \\ -0.433 & -0.394 & -0.317 & -0.257 & -0.276 \end{array}\right)$
$\pi_0^a(X)  ext{ (in bonds)} \ \pi^a(X)  ext{ (in cash)}$	4.310 4.109

# 3.2 AV@R

Definition: set-valued AV@R (static case): HAMEL, RUDLOFF, YANKOVA 12

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Let  $\alpha \in (0,1]^d$  and  $X \in L^1_d$ .

$$\begin{aligned} AV@R_{\alpha}^{reg}\left(X\right) &= \left\{ \operatorname{diag}\left(\alpha\right)^{-1}\mathbb{E}\left[Z\right] - z \colon \\ &Z \in \left(L_{d}^{1}\right)_{+}, \; X + Z - z\mathbb{1} \in \left(L_{d}^{1}\right)_{+}, \; z \in \mathbb{R}^{d} \right\} \cap M. \end{aligned}$$

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Remark: If m = d = 1: conditions  $Z \in (L_1^1)_+$  and  $X + Z - z\mathbb{1} \in (L_1^1)_+$  are equivalent to  $Z \ge (-X + z\mathbb{1})^+$  with  $X^+ = \max\{0, X\}.$ 

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$$AV@R^{sca}_{\alpha}\left(X\right) = \inf_{z \in \mathbb{R}} \left\{ \frac{1}{\alpha} E\left[ \left( -X + z \mathbb{1}\right)^{+} \right] - z \right\}$$

which is optimized certainty equivalent representation of the AV@R by Rockafellar and Uryasev '00.

B. Rudloff

Dynamic risk measures in markets with transaction costs

# 3.2 AV@R

## Good-deal bounds

The market extension  $\mathbb{R}^{mar}$  of a risk measure  $\mathbb{R}$  satisfies

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$$AV@R_{\alpha}^{mar}(X) = \bigcup \left\{ AV@R^{reg}(X - Y) : Y \in \sum_{s=0}^{T} L_{d}^{1}(K_{s}) \right\}$$
$$= \left\{ \operatorname{diag}(\alpha)^{-1} \mathbb{E}[Z] - z : \\Z \in \left(L_{d}^{1}\right)_{+}, X + Z - z\mathbb{1} \in \sum_{s=0}^{T} L_{d}^{1}(K_{s}), z \in \mathbb{R}^{d} \right\} \cap M$$

is a again set-valued coherent risk measure.

# 3.2 AV@R

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Let  $\Omega$  be finite. Then,  $AV@R^{reg}_{\alpha}(X)$  and  $AV@R^{mar}_{\alpha}(X)$  can be calculated by solving a **linear vector optimization problem** (using Benson's algorithm)

minimize P(x) with respect to  $\leq_{M_+}$  subject to  $Bx \geq b$ .

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$$AV@R^{reg}_{\alpha}\left(X\right) = \bigcap_{(Q,w)\in\mathcal{W}^{\alpha}} \left(E^{Q}\left[-X\right] + G\left(w\right)\right) \cap M,$$

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$$\mathbf{e} = (1, ..., 1)^T \in \mathbb{R}^d. \text{ Recall, } G(w) = \left\{ x \in \mathbb{R}^d \colon 0 \le w^T x \right\} \text{ and}$$
$$\mathcal{W} = \left\{ (Q, w) \in \mathcal{M}_{1,d}^P \times \mathbb{R}^d + \backslash M^{\perp} \colon \operatorname{diag} (w) \frac{dQ}{dP} \in (L_d^{\infty})_+ \right\}.$$

B. Rudloff

Dynamic risk measures in markets with transaction costs

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- can construct a multi-portfolio time consistent version of  $(AV@R_{\alpha})_t(X)$  by composition

# Construction of multi-portfolio time consistent risk measures

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• To construct a multi-portfolio time consistent version of  $(R_t)_{t=0}^T$ :

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Feinstein, Rudloff (12): Set-valued dynamic risk measures. Submitted for publication.

#### Dynamic Risk Measures in Transaction Cost Markets

# Thank you!

B. Rudloff

Dynamic risk measures in markets with transaction costs