

## Determinant point processes

(19)

The following discussion will lead to asymptotics.

Schur measure can be mapped onto a point process which has a special property of being determinantal.

- Let  $\mathcal{X}$  be a one particle state space. We will focus on discrete spaces  $\mathbb{Z}$  or  $\mathbb{N}$  (though with minor modifications  $\mathbb{R}$ )
- Let  $X$  be a (locally finite) collection of points in  $\mathcal{X}$  (i.e. element of  $\{0,1\}^{\mathcal{X}}$ ).
- A point process is a proba measure  $\mathbb{P}$  on  $\{0,1\}^{\mathcal{X}}$ .

Def<sup>n</sup> For  $A \subseteq \mathcal{X}$  finite, the correlation function for  $X$  is

$$\rho(A) = \mathbb{P}(A \subseteq X).$$

$$\text{For } |A|=n, A = \{x_1, \dots, x_n\}, \rho_n(x_1, \dots, x_n) := \rho(A).$$

Exercises

(1) For  $n \geq 1$  and a c.p.t.t. supported l.c.d. Borel function

$f$  on  $\mathcal{X}^n$  one has

$$\int_{\mathcal{X}^n} f p_n = \mathbb{E} \left( \sum_{x_{i_1}, \dots, x_{i_n} \in \mathcal{X}} f(x_{i_1}, \dots, x_{i_n}) \right)$$

2) Show that a point process on a discrete set

$\mathcal{X}$  is uniquely determined by its correlation functions

3) For  $\mathcal{X} = \mathbb{R}$  the correlation  $f^n$ 's  $p_n$  are measured

relative to Lebesgue. Show that a poisson point

process with intensity 1 has  $p_n \equiv 1$  for all  $n$ .

Def: A point process on a discrete space  $\mathcal{X}$  is

determinantal if there exists  $K: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{C}$  such that  $p_n(x_1, \dots, x_n) = \det [K(x_i, x_j)]_{i,j=1}^n$

for all  $n \geq 1$  and  $x_i \in \mathcal{X}$ . The function

$K$  is called the correlation kernel.

- A substantial reduction in the amount of data to describe it-

• History (briefly)

↳ Early 1960's Dyson in RMT

↳ 1975 Macchi considered  $K(x,y) = \overline{K(y,x)}$  "Fermionic process"

"Repel" :  $p_2(x,y) = p_1(x)p_1(y) - |K(x,y)|^2 \leq p_1(x)p_1(y)$

↳ Det. point process terminology Borodin - Olshanski '00

↳ Many sources known

- RMT / Schur processes
- Dimers on bipartite graphs.
- Unif span tree
- Non-intersecting paths
- Zeros of GAF

Schur measure is determinantal

Define  $X(\lambda)_i = \lambda_i - i + 1/2 \in \mathbb{Z} + 1/2$ .

Theorem (Okounkov '01)

Suppose  $\lambda \in Y$  distributed as  $\mathbb{S}_{p_1, p_2}$  ( $p_1, p_2$  Schur pos.)

Then  $X(\lambda)$  is a determinantal point process on  $\mathbb{Z} + 1/2$

with correlation kernel  $k(i, j)$  defined via generating series

$$\sum_{i, j \in \mathbb{Z} + 1/2} k(i, j) v^i w^j = \frac{H(p_1; v) H(p_2; w^{-1})}{H(p_2; v^{-1}) H(p_1; w)} \sum_{k = 1/2, 3/2, \dots} \left(\frac{w}{v}\right)^k$$


Where recall for  $p = (\alpha; \beta; \gamma)$ :  $H(p; z) = e^{\gamma z} \prod_{|\alpha|} \frac{1 + \beta_i z}{1 - \alpha_i z}$

- 1) Proof in Borodin-Gorin notes. based on fact that  $S_\lambda = \frac{\det(\dots)}{\det(\dots)}$ .
- 2) Earlier work: Johansson, Borodin-Oblomkov-Okounkov.
- 3) Above is a formal power series identity
- 4) Under suitable conditions can treat as analytic identity and invert via contour integral to get  $k(i, j)$ .

Let us apply to the case related to TASEP where

$$\rho_1 = (\overset{\sim}{1}, \dots, 1; 0; 0), \rho_2 = (0; 0; \tau), \tau \geq 0.$$

then  $H(\rho_1; z) = \left(\frac{1}{1-z}\right)^N$   $H(\rho_2; z) = e^{\tau z}$  so

$$K(i, j) = \frac{1}{(2\pi i)^2} \oint \oint \left(\frac{1-w}{1-v}\right)^N \frac{e^{\tau w^{-1}}}{e^{\tau v^{-1}}} \frac{\sqrt{vw}}{v-w} \frac{dv dw}{v^{i+1} w^{j+1}}$$


• From  $K$  how can we extract ~~distribution~~ distribution of  $\lambda_N$  (or equivalently  $X_N(\tau)$ )?

Note: for  $m \in \mathbb{Z}$ ,  $\mathbb{P}(X_N(\lambda) > m) = \mathbb{P}(X_N(\lambda) \cap [-\infty, m] = \emptyset)$

(see Borodin's RMT book chapter, page 3)

From inclusion/exclusion, for  $I \subseteq \mathbb{Z}$

$$\mathbb{P}(X \cap I = \emptyset) = \det(I - K_I)_{L^2(I)}$$

where  $K_I = \chi_I K \chi_I$  is  $K$  restricted to  $L^2(I)$  and

$$\det(I - K)_{L^2(I)} := 1 + \sum_{k=1}^{\infty} \frac{(-1)^k}{k!} \int_{\mathbb{Z}} \dots \int_{\mathbb{Z}} \det[K(x_i, x_j)]_{i,j=1}^k$$

"Fredholm determinant"

From such a formula, we can take asymptotics to prove the claimed TASEP limit theorems. Instead, we will first degenerate to the GUE<sub>N</sub> measure and take asymptotics there. Same in spirit but a little easier.

Lets consider the GUE<sub>N</sub>(1/2) ensemble with measure  $\frac{1}{Z} \prod_{i < j}^N |x_i - x_j|^2 \prod_{i=1}^N e^{-x_i^2} dx_i$ . By ~~this~~ scaling we want to show largest/smallest eigenvalue near  $\pm \sqrt{2N}$  with  $N^{-1/6}$  fluctuations

We will, in fact, study the limiting behavior of the correlation function  $K(x,y) : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{C}$  in three scaling regimes

By asymptotics of  $K(i,j)$  (or similar derivation)

$$K(x,y) = \frac{e^{x^2 - y^2}}{2(\pi i)^2} \oint_{\Gamma_0} \int_{-i\infty}^{i\infty} \left(\frac{w}{v}\right)^N \frac{e^{w^2 - 2wy}}{e^{v^2 - 2vx}} \frac{dv dw}{w-v}$$

technical, to make trace class kernel. Doesn't change kernel.



## Idea of steepest descent

$$\int e^{Nf(z)} dz$$

- Deform contour so  $\text{Im} f(z)$  is constant.
  - by (-R- eqs  $\text{Re} f(z)$  will be changing most rapidly along this curve
  - Find critical point (i.e. maximum) along path and then the equation localizes its value to  $e^{Nf(z_{\max})}$ .
  - Higher order corrections depend on order of the critical point
- ~~Re(z)~~
- In practice one need not always find exact steepest descent contours, just need to be able to bound integrand away from critical point.

$N \rightarrow \infty$  asymptotics.

Consider  $N \log w + w^2 - 2wy$ . We are interested in  $y \sim \sqrt{N} Y$ . So set  $w = \sqrt{N} \tilde{w}$ ,  $v = \sqrt{N} \tilde{v}$

and  $Y = \sqrt{N} Y - \tilde{y}$ ,  $X = \sqrt{N} X - \tilde{x}$ . Then the kernel becomes,

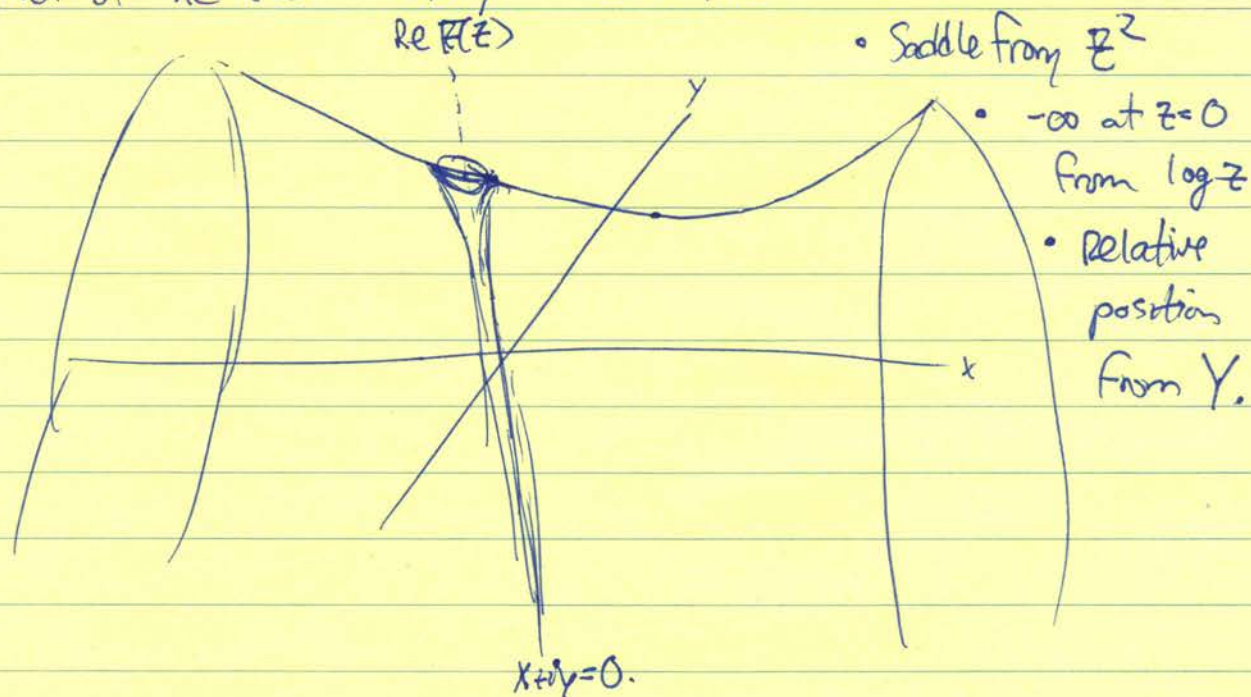
$$\frac{\sqrt{N}}{2(\pi i)^2} \oint_{\Gamma_0} \int_{-i\infty}^{i\infty} \frac{e^{NF(\tilde{w})}}{e^{NF(\tilde{v})}} \frac{e^{2\sqrt{N}\tilde{w}\tilde{y}}}{e^{2\sqrt{N}\tilde{v}\tilde{x}}} \frac{d\tilde{v}d\tilde{w}}{\tilde{w}-\tilde{v}}$$

with  $F(z) = \log z + z^2 - 2zY$ . We want to find a

set of contours along which  $F(\tilde{w})$  and  $F(\tilde{v})$  are not oscillatory,

and on which  $\text{Re}F(\tilde{w})$  is minimized and  $\text{Re}F(\tilde{v})$  maximized.

Plot of  $\text{Re}F(z)$  ( $z=x+iy$ ) looks like





Saddle point is where  $\frac{\partial \text{Re} F}{\partial \text{Re} z} = \frac{\partial \text{Re} F}{\partial \text{Im} z} = 0$

which by Cauchy-Riemann is when  $F'(z) = \frac{1}{z} + 2z - 2Y = 0$ .

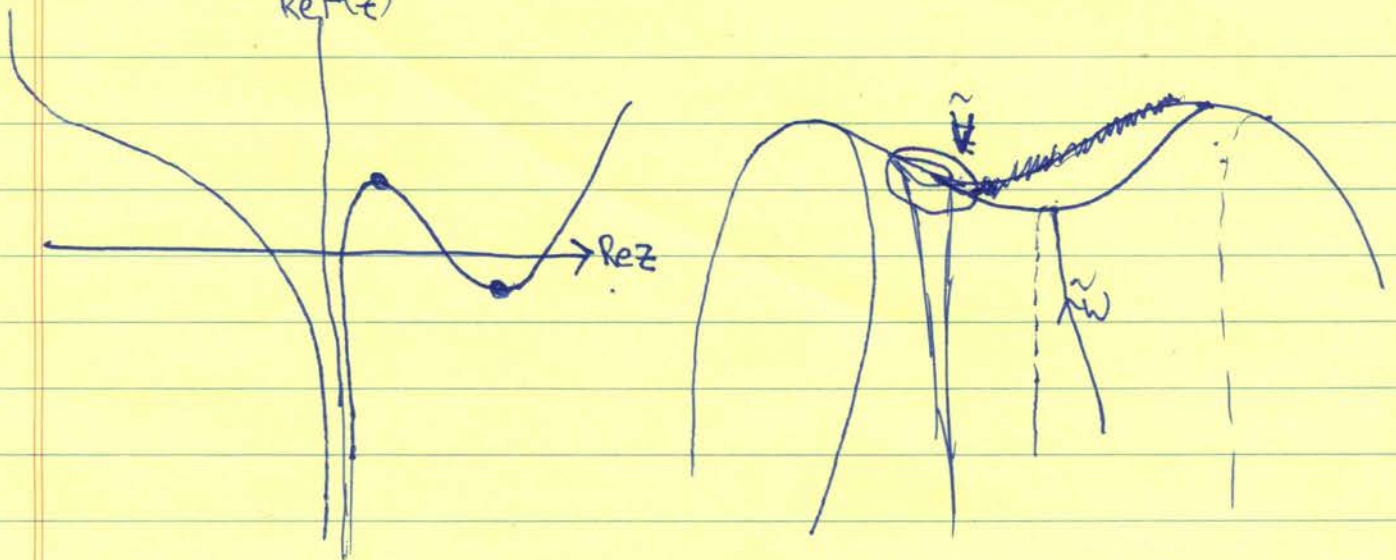
i.e.  $z = \frac{2Y \pm \sqrt{4(Y^2 - 2)}}{4}$

(a) If  $|Y| > \sqrt{2}$  then two real, positive roots

(b) If  $|Y| = \sqrt{2}$  double roots at  $\frac{1}{\sqrt{2}}$ .

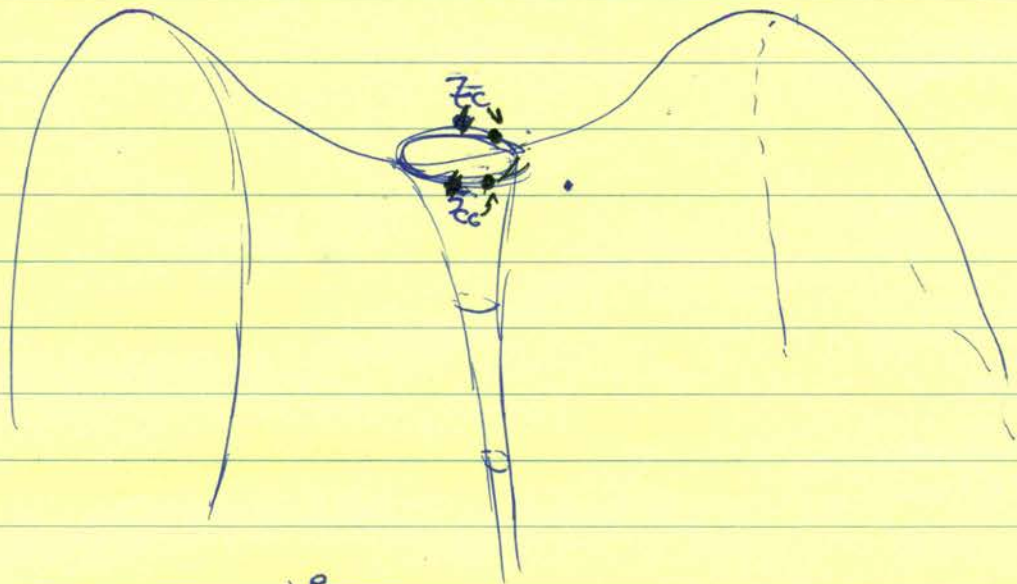
(c) If  $|Y| < \sqrt{2}$  Complex conjugate roots.

Case (a):

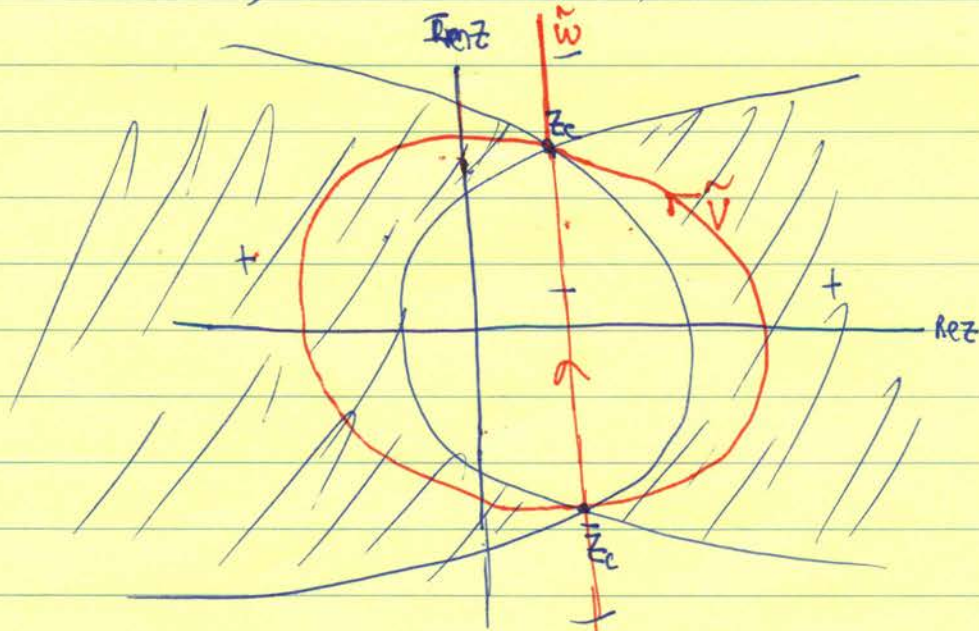


Can choose  $\tilde{v}$  and  $\tilde{w}$  contours so that  $\text{Re}(\tilde{v}) > \text{Re}(\tilde{w})$  on whole contour. Hence integral goes to zero as  $N \rightarrow \infty$  exponentially fast!

Case (c): Critical pts  $z_c, \bar{z}_c = \frac{y \pm \sqrt{y^2 - 2}}{2}$



The curves <sup>where</sup>  $\operatorname{Re} F = \operatorname{Re} F(z_c)$  have form



Since  $\operatorname{Re} F(\tilde{v}) \geq \operatorname{Re} F(z_c) \geq \operatorname{Re} F(\tilde{w})$  (with strict inequality away from  $z_c, \bar{z}_c$ )  
the integral over these contours goes to zero.

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But, in deforming from original contours to these, we crossed poles at  $\tilde{w} - \tilde{v} = 0$  and picked up a residue

$$\text{equal to } \frac{1}{\pi i} \int_{\tilde{z}_c}^{\tilde{z}_c} e^{2z(x-y)\sqrt{N}} dz = \frac{\sin(2\text{Im}z_c(x-y)\sqrt{N})}{\pi(x-y)\sqrt{N}}.$$

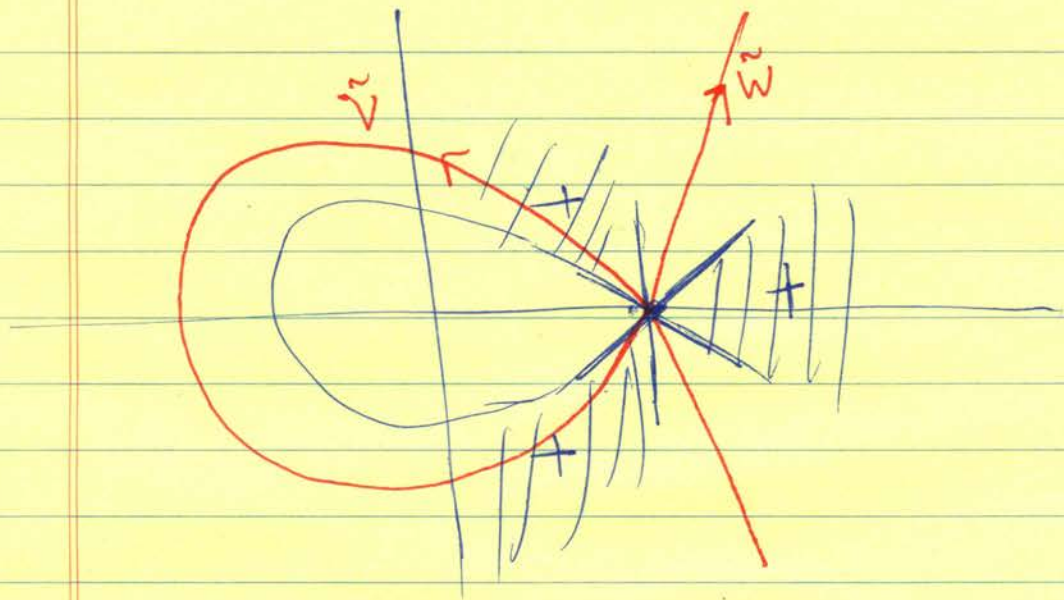
Thus

$$\lim_{N \rightarrow \infty} \frac{1}{\sqrt{N}} K_N\left(\sqrt{N}Y + \frac{\tilde{x}}{\sqrt{N}}, \sqrt{N}Y + \frac{\tilde{y}}{\sqrt{N}}\right) = \frac{\sin(2\text{Im}z_c(x-\tilde{y}))}{\pi(x-\tilde{y})}.$$

$$\text{where } 2\text{Im}(z_c) = \sqrt{2-Y^2}.$$

This is Dyson's Sine kernel and  $\sqrt{2-Y^2}$  is the Wigner semi-circle density.

Case (b):  $Y = \sqrt{2}$  then  $z_c = \bar{z}_c = \frac{1}{\sqrt{2}}$ , Consider  $\text{Re} F(z)$  near  $z_c$



so near  $z_c$   $F(z) = \frac{2\sqrt{2}}{3} (z - z_c)^3 + \dots$

Note away from  $z_c$ ,  $\text{Re} F(\tilde{v}) > \text{Re} F(z_c) > \text{Re} F(\tilde{w})$

Localize integral near  $z_c$ . Scale  $\tilde{w} = z_c + N^{1/3} \frac{w'}{\sqrt{2}}$   
 $\tilde{v} = z_c + N^{1/3} \frac{v'}{\sqrt{2}}$   
 and  $\tilde{x} = N^{1/6} \frac{x'}{\sqrt{2}}$ ,  $\tilde{y} = N^{1/6} \frac{y'}{\sqrt{2}}$  then (upto gauge transform)

$$K_N(x, y) \approx N^{1/6} \sqrt{2} \frac{1}{(2\pi i)^2} \iint \frac{e^{\frac{(w')^3}{3} - w'y'}}{e^{\frac{(v')^3}{3} - v'x'}} \frac{dv'dw'}{w'-v'}$$

So

$$\lim_{N \rightarrow \infty} \frac{K_N \left( \sqrt{2N} + \frac{x}{\sqrt{2N}^{1/6}}, \sqrt{2N} + \frac{y}{\sqrt{2N}^{1/6}} \right)}{\sqrt{2N}^{1/6}} = A(x, y)$$

where

$$A(x, y) = \frac{1}{2\pi i} \int \frac{e^{w^{3/3} - wy}}{e^{v^{3/3} - vx}} \frac{dv dw}{(w-v)}$$

or equiv

$$= \frac{Ai(x) Ai'(y) - Ai'(x) Ai(y)}{x-y}$$

with  $Ai(s) = \frac{1}{2\pi i} \int_{\mathcal{K}} e^{z^{3/3} - zs} dz$  the Airy function

(equiv has  $Ai''(s) = s Ai(s)$ ,  $Ai(s) \rightarrow 0$  exp fast as  $s \rightarrow \infty$ )

or equiv.

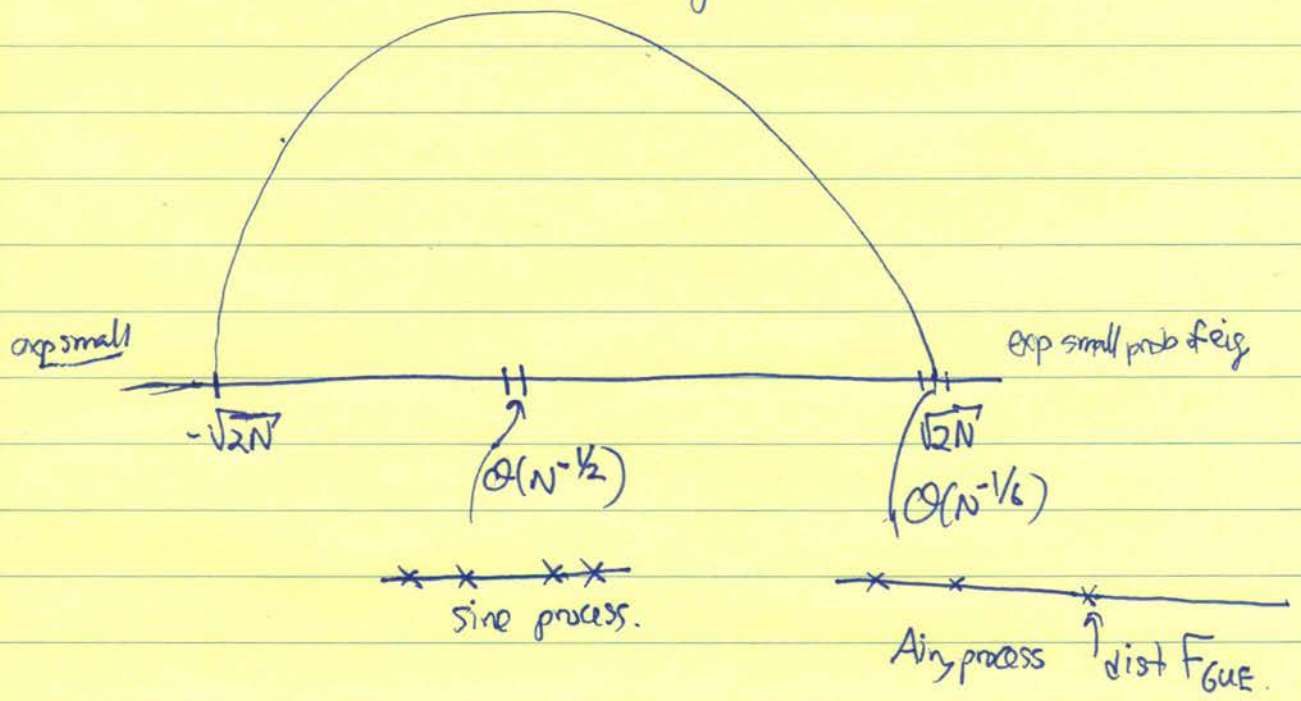
$$= \int_{-\infty}^0 Ai(x-r) Ai(y-r) dr$$

Exercise: Show equivalence of them all.

Note that

$$F_{\text{GUE}}(s) = \det(I - K_{\mathbb{A}})_{L^2(s, \infty)} \quad \square$$

To summarize: Plot eigenvalues of  $(\mathcal{U}E_N)^{1/2}$



# Schur process

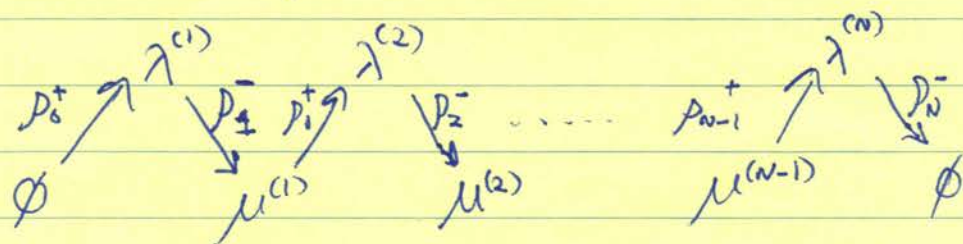
Okounkov - Reshetikhin '01.

Def Schur process of rank  $N$  is a probability measure on seq of Young diagrams  $\lambda^{(1)}, \mu^{(1)}, \lambda^{(2)}, \mu^{(2)}, \dots, \mu^{(N-1)}, \lambda^{(N)}$  parameterized by  $2N$  Schur-positive specializations  $p_0^+, p_1^-, p_1^+, p_2^-, p_2^+, \dots, p_N^-$  and given by

$$P(\lambda^{(1)}, \mu^{(1)}, \lambda^{(2)}, \dots, \lambda^{(N)}) = \frac{1}{Z} S_{\lambda^{(1)}}(p_0^+) S_{\lambda^{(1)}/\mu^{(1)}}(p_0^-) S_{\lambda^{(2)}/\mu^{(1)}}(p_1^+) S_{\lambda^{(2)}/\mu^{(2)}}(p_1^-) \dots S_{\lambda^{(N)}/\mu^{(N-1)}}(p_{N-1}^+) S_{\lambda^{(N)}}(p_N^-)$$

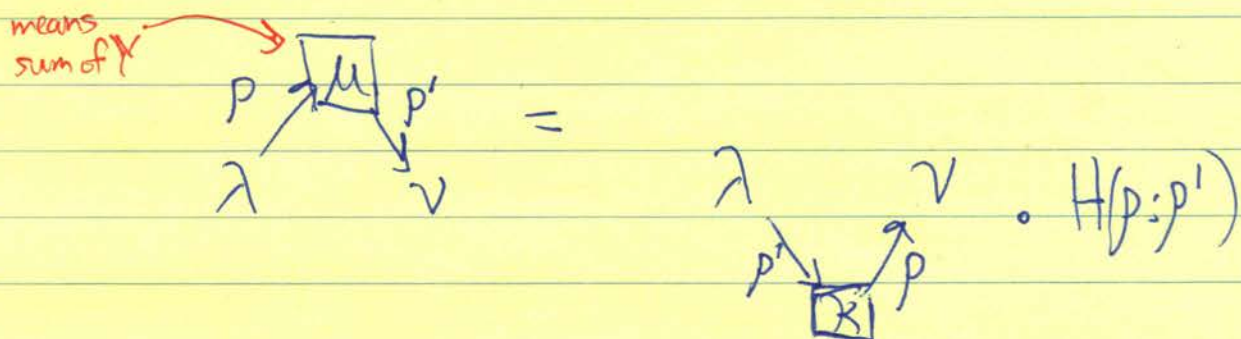
Definition implies  $\lambda^{(1)} \supset \mu^{(1)} \subset \lambda^{(2)} \supset \mu^{(2)} \subset \dots \supset \mu^{(N-1)} \subset \lambda^{(N)}$

We pictorially illustrate this as

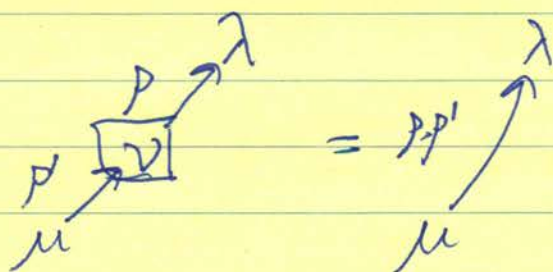


We will use skew Cauchy, Chapman-Kolmogorov at length.

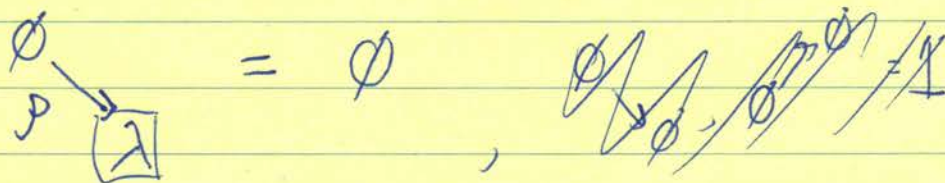
Skew Cauchy  $\sum_{\mu \in Y} S_{\mu/\lambda}(p) S_{\mu/\nu}(p') = H(p;p') \sum_k S_{\lambda/k}(p') S_{\nu/k}(p)$



Chapman-Kolmogorov:  $\sum_{\nu \in Y} S_{\lambda/\nu}(p) S_{\nu/\mu}(p') = S_{\lambda/\mu}(p;p')$



Zero rule.  $S_{\emptyset/\lambda} = \begin{cases} 1 & \lambda = \emptyset \\ 0 & \text{else} \end{cases}$

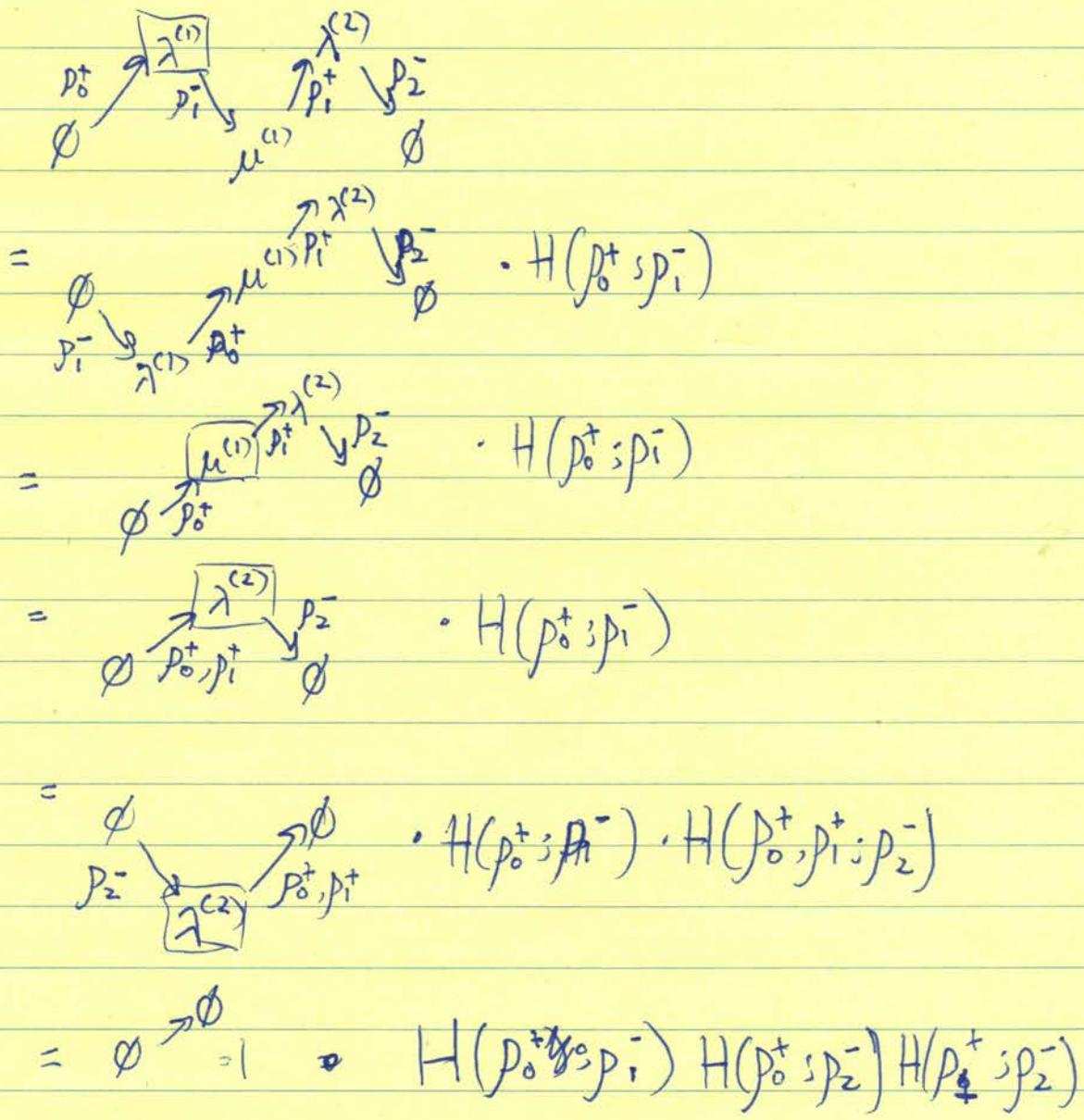




Claim: The normalizing constant  $Z$  is Schur process is

$$Z = \prod_{i < j} H(p_i^+ : p_j^-)$$

PF:

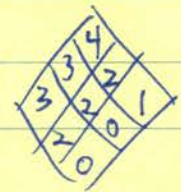



Note from defn:  $H(p_1, p_2, \dots, p_m) = \prod_{i=1}^k \prod_{j=1}^m H(p_i : p_j)$

□

- In a similar way, one shows that the projection of Schur process to  $\lambda^{(k)}$  is Schur measure  $S_{p_1, p_2}$  with  $p_1 = (p_0^+, p_1^+, \dots, p_{k-1}^+)$ ,  $p_2 = (p_k^-, p_{k+1}^-, \dots, p_n^-)$
- Just like Schur measure, Schur process gives rise to a determinant point process.

Exercise <sup>Good</sup> Plane partitions with  $q^{rd}$  measure are Schur processes.

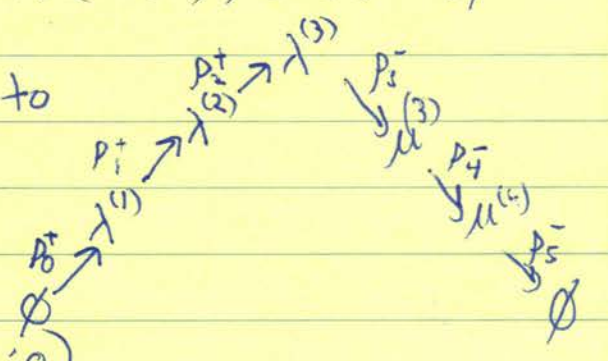
A boxed plane partition  $\Pi =$   such that    
 $vol \Pi = \sum entries$ ,  $0 < q < 1$ . Project this measure onto

a seq<sup>n</sup> of partitions  $\emptyset, (3), (3,2), (4,2,0), (2,0), (1), \emptyset$ .

Claim: This is distributed according to

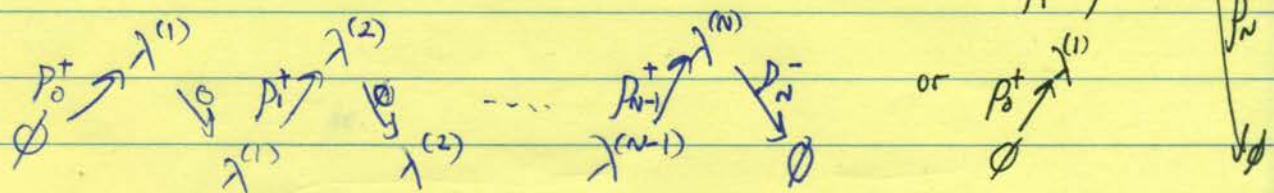
(Where all missing spec. are 0 and.

$$p_j^+ = ((q^{-j})_{i=0,0}) ; p_j^- = ((q^j)_{i=0,0})$$



Hint: recall that for  $\alpha_i = c$  and all else in  $p, 0$ ,  $S_{\lambda \mu} = \begin{cases} c^{|\lambda| - |\mu|} & \text{hor. strip} \\ 0 & \text{0} \end{cases}$

Def<sup>n</sup>: Ascending Schur process has form.



Can write as  $0 \subseteq \lambda^{(1)} \subseteq \lambda^{(2)} \subseteq \dots \subseteq \lambda^{(n)}$ ,

and is specified by  $p_0^+, p_1^+, \dots, p_{n-1}^+, p_n^-$  according to the measure

$$\frac{S_{\lambda^{(1)}}(p_0^+) S_{\lambda^{(2)}/\lambda^{(1)}}(p_1^+) \dots S_{\lambda^{(n)}/\lambda^{(n-1)}}(p_{n-1}^+) S_{\lambda^{(n)}}(p_n^-)}{H(p_0^+, p_1^+, \dots, p_{n-1}^+, p_n^-)}$$

It is not hard to come up with Markov operators (stochastic matrices) that act well on Schur-measure and ultimately which act well on Schur-process

Def: For  $p, p'$  Schur pos. specializations with  $H(p, p') < \infty$   
 define matrices  $P_{\lambda \rightarrow \mu}^{\uparrow}(p, p')$ ,  $P_{\lambda \rightarrow \mu}^{\downarrow}(p, p')$  with rows  
 and column indexed by Young diagrams  $\lambda$  and  $\mu$  as follows

- $P_{\lambda \rightarrow \mu}^{\uparrow}(p, p') := \frac{S_{\mu}(p)}{S_{\lambda}(p)} \cdot \frac{S_{\mu\lambda}(p')}{H(p, p')}$

- $P_{\lambda \rightarrow \mu}^{\downarrow}(p, p') := \frac{S_{\mu}(p)}{S_{\lambda}(p, p')} S_{\lambda\mu}(p')$

Prop  $P_{\lambda \rightarrow \mu}^{\uparrow}$  and  $P_{\lambda \rightarrow \mu}^{\downarrow}$  are stochastic (i.e. non-neg and

for all  $\lambda \in Y$  (1)  $\sum_{\mu} P_{\lambda \rightarrow \mu}^{\uparrow}(p, p') = 1$   
 (2)  $\sum_{\mu} P_{\lambda \rightarrow \mu}^{\downarrow}(p, p') = 1$ )

Pf : Non-neg follows from Schur-pos. spec.

(1) from skew Cauchy (2) from Chap-Kol.

Thus  $P_{\lambda \rightarrow \mu}^{\uparrow}, P_{\lambda \rightarrow \mu}^{\downarrow}$  can be viewed as transition prob. for Markov Chains.

where  $P_{\lambda \rightarrow \mu}^{\uparrow} = 0$  unless  $\mu \supset \lambda$  "increases"

$P_{\lambda \rightarrow \mu}^{\downarrow} = 0$  unless  $\mu \subset \lambda$  "decreases"

These transition matrices present class of Schur measures.

Prop For any  $\mu \in Y$

$$(1) \sum_{\lambda \in Y} S_{\rho_1, \rho_2}(\lambda) P_{\lambda \rightarrow \mu}^{\uparrow}(\rho_2, \rho_3) = S_{\rho_1, \rho_3, \rho_2}(\mu)$$

$$(2) \sum_{\lambda \in Y} S_{\rho_1, \rho_2, \rho_3}(\lambda) P_{\lambda \rightarrow \mu}^{\downarrow}(\rho_2, \rho_3) = S_{\rho_1, \rho_2}(\mu)$$

Pf (1) By Chap. kol (2) By Skew Cauchy.

Example In the limit discussed earlier to  $GUE_N$  here is what happens.

- $P_{\lambda \rightarrow \mu}^{\uparrow}$  becomes  $\frac{V(y)}{V(x)} \Delta$  where  $\Delta$  Dirichlet Laplacian on  $X_1 > X_2 > \dots > X_N$  and  $V(x) = \prod_{i < j} (x_i - x_j)$

This is the generator of a stoch. process called Dyson BM which maps  $GUE_N(t) \rightarrow GUE_N(t+dt)$

- $P_{\lambda \rightarrow \mu}^{\downarrow}$  becomes indicator function that  $X_1 > y_1 > X_2 > y_2 \dots > y_{N-1} > X_N$  and maps  $GUE_N(t) \rightarrow GUE_{N-1}(t)$ .
- The ascending Schur process becomes the GUE minor process which is measure of eigenvalues of  $N \times N, (N-1) \times (N-1), \dots, 1 \times 1$  principle minors.

In general a Schur process can be written as a trajectory of a Markov chain involving  $P^\uparrow, P^\downarrow$  with particular specializations.

Ascending Schur process  $\emptyset \subset \lambda^{(1)} \subset \dots \subset \lambda^{(N)}$  with  $p_0^+, \dots, p_{N-1}^+, p_N^-$  spec.

equals  $\mathbb{S}_{p_0^+, \dots, p_{N-1}^+, p_N^-}(\lambda^{(N)}) P_{\lambda^{(N)} \rightarrow \lambda^{(N-1)}}^\downarrow(p_0^+, \dots, p_{N-2}^+, p_{N-1}^+) \dots P_{\lambda^{(2)} \rightarrow \lambda^{(1)}}^\downarrow(p_0^+, p_1^+)$

Exercise: Figure out how this works in general.

Prop:  $P^\uparrow(p_1, p_2, p_3) P^\downarrow(p_1, p_2) = P^\downarrow(p_1, p_2) P^\uparrow(p_1, p_3)$

This means that on Schur processes

$$\mathbb{S}_{p_4, p_1, p_2} P^\uparrow(p_1, p_2, p_3) = \mathbb{S}_{p_3, p_4, p_1, p_2}$$

$$\mathbb{S}_{p_3, p_4, p_1, p_2} P^\downarrow(p_1, p_2) = \mathbb{S}_{p_3, p_4, p_1}$$

and  $\mathbb{S}_{p_4, p_1, p_2} P^\downarrow(p_1, p_2) = \mathbb{S}_{p_4, p_1}$

$$\mathbb{S}_{p_4, p_1} P^\uparrow(p_1, p_2) = \mathbb{S}_{p_3, p_4, p_1}$$

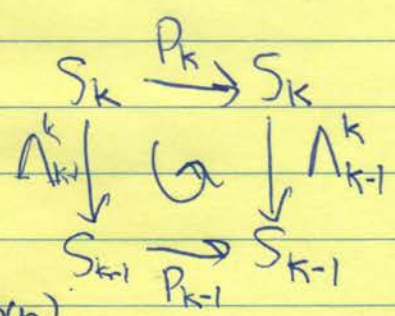
We will use this commutation relation to build dynamics preserving Schur processes.

# A general construction of multivariate Markov Chains

(or an exact sampling method for certain types of Gibbs measures)

- Let  $(S_1, \dots, S_n)$  n-tuple of discrete (countable) sets
- $P_k: S_k \times S_k \rightarrow [0,1]$  st.  $\sum_{y \in S_k} P_k(x,y) = 1 \quad \forall x \in S_k$
- $\Delta_{k-1}^k: S_k \times S_{k-1} \rightarrow [0,1]$  st.  $\sum_{y \in S_{k-1}} \Delta_{k-1}^k(x,y) = 1 \quad \forall x \in S_k$

Assume  $\Delta_{k-1}^k := \Delta_{k-1}^{k-1} P_{k-1} = P_k \Delta_{k-1}^k$



Then we can define a multivariate

Markov chain with transition matrix  $P^{(n)}$

and state space  $S^{(n)} = \{ (x_1, \dots, x_n) \in S_1 \times \dots \times S_n : \prod_{k=2}^n \Delta_{k-1}^k(x_k, x_{k-1}) > 0 \}$

via  $(\bar{X}_n = (X_1, \dots, X_n), \bar{Y}_n = (Y_1, \dots, Y_n))$

$$P^{(n)}(\bar{X}_n, \bar{Y}_n) = P_1(x_1, y_1) \prod_{k=2}^n \frac{P_k(x_k, y_k) \Delta_{k-1}^k(x_k, x_{k-1})}{\Delta_{k-1}^k(x_k, y_{k-1})}$$

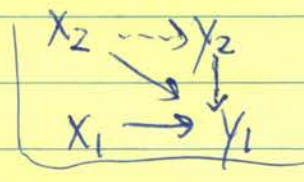
if  $\prod_{k=2}^n \Delta_{k-1}^k(x_k, y_{k-1}) > 0$  and 0 otherwise.

This means that we sequentially update  $X$  starting at  $X_1$ .

We choose  $y_1$  according to  $P_1(x_1, y_1)$ , then

choose  $y_2$  according to 
$$\frac{P_2(x_2, y_2) \Delta_1^2(y_2, y_1)}{\Delta_1^2(x_2, y_1)}$$

which is conditional dist. of application of  $P_2$  the  $\Delta_1^2$  conditioned on starting at  $x_2$  and finishing at  $y_1$ , and repeats

Prop Let  $m_n$  be prob measure on  $S_n$  and define 

$$m^{(n)}(X) = m_n(x_n) \Delta_{n-1}^n(x_n, x_{n-1}) \dots \Delta_1^2(x_2, x_1)$$

Set  $\tilde{m}_n = m_n P_n$  and

$$\tilde{m}^{(n)}(X) = \tilde{m}_n(x_n) \Delta_{n-1}^n(x_n, x_{n-1}) \dots \Delta_1^2(x_2, x_1)$$

Then  $m^{(n)} P^{(n)} = \tilde{m}^{(n)}$ .

Pf: Repeated application of computer relation.

Remark: The marginal of these dynamics on level  $k$  is  $P_k$  (i.e. all of the  $P_k$  chains are linked together)



Let us apply this construction with

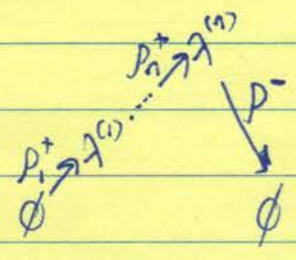
$$S_i = Y, \quad P_k(\lambda, \mu) = P_{\lambda \rightarrow \mu}^+(\rho_1^+, \dots, \rho_k^+; \rho^-)$$

$$\Lambda_{k-1}^k(\lambda, \mu) = P_{\lambda \rightarrow \mu}^-(\rho_1^+, \dots, \rho_{k-1}^+; \rho_k^+)$$

$$\text{Thesis } S^{(n)} = \{ (\lambda^{(1)} \leftarrow \lambda^{(2)} \leftarrow \dots \leftarrow \lambda^{(n)}) \mid \prod_{k=2}^n \Lambda_{k-1}^k(\lambda^{(k)}, \lambda^{(k-1)}) \neq 0 \}$$

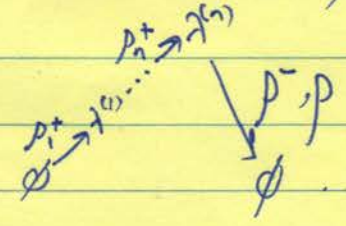
$$\text{and } m_n(\lambda^{(n)}) = \int P_{\lambda^{(n)} \rightarrow \emptyset}^+(\rho_1^+, \dots, \rho_n^+; \rho^-)$$

Then as we saw before  $m^{(n)}(\lambda^{(1)} \leftarrow \dots \leftarrow \lambda^{(n)}) = \text{Schur process}$



The previous construction implies that the Markov dynamics on

$\lambda^{(1)} \leftarrow \dots \leftarrow \lambda^{(n)}$  takes the Schur process to



↳ Hence, if we start with an <sup>ascending</sup> Schur process, we will have

(marginally) another Schur process after any number of steps,

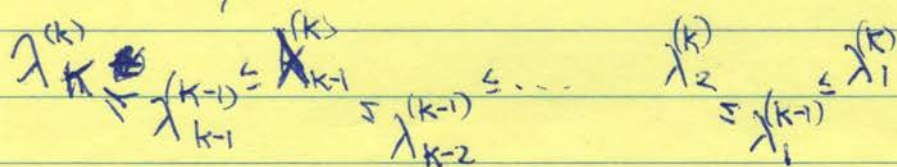
but with new parameters in the specialization  $\rho^-$ .

There are several natural/simple examples of such dynamics. We consider 1

- Take  $p_k^+ = ((1); 0; 0) \forall k$  and  $p^- = (0; (b); 0)$
- Consider the discrete time Markov chain  $\lambda(t) = (\lambda^{(1)}(t) \leftarrow \lambda^{(2)}(t) \leftarrow \dots \leftarrow \lambda^{(n)}(t))$  with  $p^-$  initially 0, hence  $\lambda(0) = (\emptyset \leftarrow \dots \leftarrow \emptyset)$ .
- After time  $t$ , the marginal on  $\lambda^{(k)}(t)$  is  $\sum_{\substack{p_{i_1}^+ \dots p_{i_t}^+ \\ (1, \dots, 1) \leq 0; 0}} p_{i_1}^+ \dots p_{i_t}^+ = (0; (b, \dots, b) \leq 0)$ , and hence supported on diagrams of at most  $k$  non-empty rows.

The condition  $\Delta_{k-1}^k(\lambda^{(k)}, \lambda^{(k-1)}) > 0$  implies  $S_{\lambda^{(k)}/\lambda^{(k-1)}}((1); 0; 0) > 0$

which is only true if  $\lambda^{(k)} = \lambda^{(k-1)} + \text{horizontal strip}$ . This means



and is written as  $\lambda^{(k-1)} \leq \lambda^{(k)}$  meaning they interlace.

~~$\lambda^{(1)}$  has a single row, hence is one number (as a partition).~~

~~$$p_{\lambda^{(1)}/\lambda^{(0)}}(p_i; p') = H(p_i; p') \cdot \begin{cases} b & \mu = \lambda + 1 \\ 1 & \mu = \lambda \end{cases}$$~~

- Consider evolution of  $\lambda^{(i)}(t)$ , which is one rowed, hence a single number.

$$P_{\lambda^{(i)} \rightarrow \mu^{(i)}}^{\uparrow}(\rho_i^+; \rho') = \frac{S_{\mu^{(i)} / \lambda^{(i)}}(1|0; 0)}{S_{\lambda^{(i)} / \lambda^{(i)}}(1|0; 0)} \cdot \frac{S_{\lambda^{(i)} / \lambda^{(i)}}(0; b| 0)}{H((1|0; 0) | (0; b| 0))}$$

$$S_{\mu / \lambda}(0; b| 0) > 0 \text{ if}$$

$\mu / \lambda$  vertical strip

$$= \frac{1}{1+b} \cdot \begin{cases} b & \mu^{(i)} = \lambda^{(i)} + 1 \\ 1 & \mu^{(i)} = \lambda^{(i)} \end{cases}$$



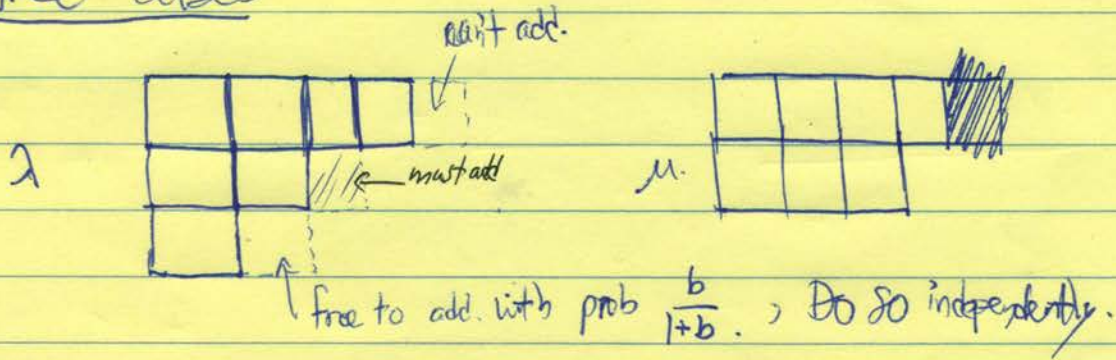
So  $\lambda^{(i)}(t)$  ~~decreases~~ ~~increases~~ increases by 1 with prob  $\frac{b}{1+b}$  and otherwise stays same.

- How does  $\lambda^{(k)}(t+1)$  evolve given  $\lambda^{(k)}(t)$  and  $\lambda^{(k-1)}(t+1)$

(call  $\lambda^{(k)}(t+1) = \nu$ ,  $\lambda^{(k)}(t) = \lambda$ ,  $\lambda^{(k-1)}(t+1) = \mu$ , then

$$P(\nu | \lambda, \mu) = \frac{S_{\nu / \lambda}(0; b| 0) S_{\nu / \mu}(1| 0; 0)}{\sum_{\eta} S_{\eta / \lambda}(0; b| 0) S_{\eta / \mu}(1| 0; 0)}$$

### Three cases



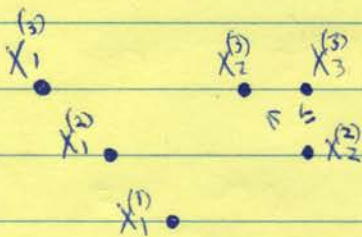
must have  $\mu \leq \nu$  and  $\nu \wedge$  vertical strip.

In order to better visualize these dynamics define

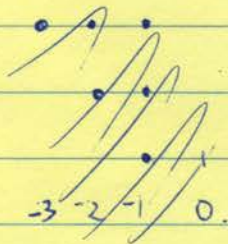
$$X_i^{(j)} = \lambda_{j+1-i}^{(j)} - N + i \quad (\text{i.e. reorder coordinates and make strictly increasing})$$

The intertwining rule becomes  $X_{i-1}^{(j)} < X_{i-1}^{(j-1)} \leq X_i^{(j)}$

### Gelfand-Tsetlin Pattern



initial data



Dynamics • Start at level 1 update

$$X_i^{(1)}(t+1) = X_i^{(1)}(t) + \begin{cases} 1 & \text{prob } \frac{b}{1+b} \\ 0 & \text{prob } \frac{1}{1+b} \end{cases}$$

• For level  $k$ , if  $X_i^{(k)}(t) = X_{i-1}^{(k-1)}(t+1) - 1$  then  $X_i^{(k)}$  is pushed by

$$X_{i-1}^{(k-1)} \text{ so that } X_i^{(k)}(t+1) = X_i^{(k)}(t) + 1 \quad \rightarrow$$

• For level  $k$ , if  $X_i^{(k-1)}(t+1) = X_i^{(k)}(t) + 1$ , particle  $X_i^{(k)}$  is blocked by

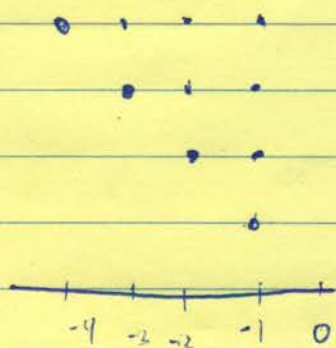
$$X_i^{(k-1)} \text{ and } X_i^{(k)}(t+1) = X_i^{(k)}(t) \quad \rightarrow$$

• Otherwise  $X_i^{(k)}(t+1) = X_i^{(k)}(t) + \begin{cases} 1 & \text{prob } \frac{b}{1+b} \\ 0 & \text{prob } \frac{1}{1+b} \end{cases}$

Show simulation

If we start with  $p^- = 0$  then the measure is delta on  $\delta(c_1 \dots c_n)$

or



Running one step is like taking

$$p^- \rightarrow (p^-, \underbrace{(0, \dots, 0)}_t)$$

so that after time  $t$

$$\lambda(t) = \left( \lambda^{(1)} \leq \lambda^{(2)} \leq \dots \leq \lambda^{(n)} \right) \text{ is distributed}$$

as a Schur process with  $p_i^+ = \dots = p_n^+ = 1$  and  $p_i^- = \underbrace{(0, \dots, 0)}_t$

and  $\lambda^{(n)}$  is marginally distributed as

$$\mathcal{S}(\underbrace{(1, \dots, 1)}_n; \underbrace{(0, \dots, 0)}_t) (\lambda^{(n)})$$

• Observe that the left edge  $X_1^{(1)}(t), X_1^{(2)}(t), \dots, X_1^{(n)}(t)$  is marginally a Markov process with ~~right to left~~ right to left subsequential update



Close to TASEP, but discrete time.

We can take a continuous time (Poisson) limit of these dynamics

- Let  $b = \varepsilon$ ,  $t = \varepsilon' \tau$  then the edge dynamics becomes TASEP
- The limit of  $\rho' = (0; \underbrace{(\varepsilon, \dots, \varepsilon)}_{\varepsilon' \tau}; 0)$  is  $(0; 0; \tau)$

• This proves that if  $\lambda^{(n)}$  distributed according to  $S_{(1, \dots, 1; 0; 0)}^{(n)}$  is  $(0; 0; \tau)$

then  $\lambda^{(n)} - n$  is distributed as the  $n^{\text{th}}$  particle left in TASEP

with  $x_1^{(k)}(0) = -k$  (step initial data)

Can then apply det. point process technology to get <sup>marginal</sup> distributions

and take limit (analog of GUE limit)

• Full  $2^d$  dynamics have limit in which each particle ~~has~~ <sup>at</sup> rate 1

jumps right unless blocked <sup>from below</sup>, and particles push those above it

(higher particles ~~are~~ defer to lower particles)

Finally, can take a diffusive scaling limit.

$$Y_j^{(k)}(t) = \lim_{\epsilon \rightarrow 0} \epsilon^{1/2} \left( X_j^{(k)}\left(\frac{t}{\epsilon}\right) - \epsilon^{-1}t \right)$$

We saw before that  $Y^{(k)}$  distributed as  $GUE_k(t)$ . The dynamics become the following:

$Y_1^{(1)}(t)$  performs a Brownian motion.

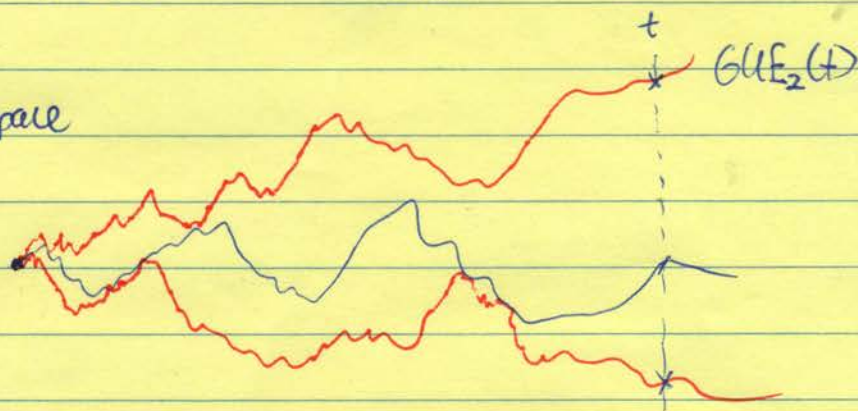
$Y_j^{(k)}(t)$  performs a Brownian motion, reflected off  $Y_j^{(k+1)}(t), Y_{j-1}^{(k-1)}(t)$ .

• The ensemble at time  $t$  is  $GUE$  minor distributed.

• The  $\{Y_j^{(k)}(t)\}_{k=1}^n$  is a ctrs space

TASEP with BM's reflected off

the one to the right.



This is called Warren's process.

When we move onto Macdonald processes we will go through a similar degeneration, though with additional parameters which give access to many new, and interesting, prob. models.