

General relativity. Problem set 1.

HS 17

Due: Tue, September 26, 2017

1. The sphere as a manifold

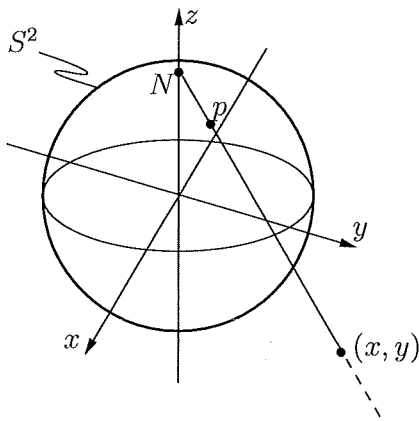
Consider the sphere

$$S^2 = \{p = (x_1, x_2, x_3) \mid x_1^2 + x_2^2 + x_3^2 = 1\}$$

and its covering $S^2 = U_+ \cup U_-$ by the two open sets

$$U_{\pm} = S^2 \setminus \{(0, 0, \pm 1)\}$$

obtained by removing the north, resp. south pole from S^2 . The stereographic projection $p \mapsto (x, y)$ shown in the figure provides a chart for U_+ with coordinate neighborhood $\mathbb{R}^2 \ni (x, y)$; similarly there is one for U_- with neighborhood $\mathbb{R}^2 \ni (\bar{x}, \bar{y})$. On which subset of \mathbb{R}^2 is the transition function $(x, y) \mapsto (\bar{x}, \bar{y})$ defined? Compute that function.



2. Tensors

a) Show that not all tensors in

$$\begin{aligned} V \otimes V &= \{T \mid T \text{ is a bilinear form over } V^* \times V^*\} \\ &= \{\text{linear combinations of tensors } v_1 \otimes v_2 \mid v_1, v_2 \in V\} \end{aligned}$$

are of the form $v_1 \otimes v_2$ (simple tensors).

b) Identify $V \otimes W^*$ with the linear space $\mathcal{L}(W, V)$ of linear maps $W \rightarrow V$.

GR - HW # 1 Solutions

20/9/2017

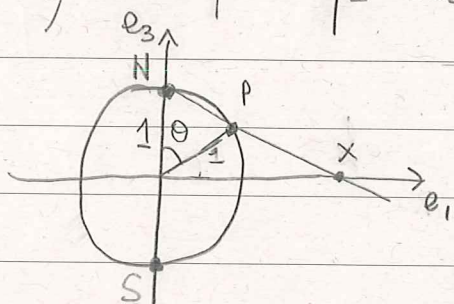
1

Q1 The Sphere as a Manifold

$$S^2 := \{x \in \mathbb{R}^3 \mid \|x\| = 1\} = \overset{\text{zero set}}{(\|\cdot\| - 1)^{-1}(\{0\})}$$

Define $U_{\pm} := S^2 \setminus \{\pm e_3\}$ where $\{e_i\}_{i=1}^3$ is the std. basis of \mathbb{R}^3 .

Define maps $\eta_{\pm}: U_{\pm} \rightarrow \mathbb{R}^2$ by stereographic proj:



$\eta_{-}: P \mapsto x$ defined $\forall P \in S^2 \setminus \{N\}$.
 given by the formula
 $\eta_{-}(\theta) = \text{ctg}(\theta/2)$ on the plane $y=0$.

Outside of the plane we rotate by the azimuthal angle φ :

$$\eta_{-}(\theta, \varphi) = \text{ctg}(\theta/2) e_r + \varphi e_{\varphi}$$

We can then convert this to Cartesian coordinates:

$$\eta_{-}(x, y, z) = \text{ctg}\left(\frac{\arctg\left(\frac{z}{\sqrt{x^2+y^2}}\right)}{2}\right) \left(\cos\left(\arctg\left(\frac{y}{x}\right)\right)e_1 + \sin\left(\arctg\left(\frac{y}{x}\right)\right)e_2\right) +$$

$$+ \arctg\left(\frac{y}{x}\right) \left(-\sin\left(\arctg\left(\frac{y}{x}\right)\right)e_1 + \cos\left(\arctg\left(\frac{y}{x}\right)\right)e_2\right)$$

Note the relations $\sin(\arctg(\alpha)) = \frac{\alpha}{\sqrt{1+\alpha^2}}$, $\cos(\arctg(\alpha)) = \frac{1}{\sqrt{1+\alpha^2}}$

$$\text{ctg}\left(\frac{1}{2}\arctg(\alpha)\right) = \frac{1+\sqrt{1+\alpha^2}}{\alpha}, \quad x^2+y^2+z^2=1$$

to get $\eta_{-}(x, y, z) = \frac{1}{1-z}(xe_1 + ye_2) \quad \forall (x, y, z) \in S^2 \setminus \{N\}$.

Similarly, $\eta_{+}(x, y, z) = \frac{1}{1+z}(xe_1 + ye_2)$

Cl₁ $U_{\pm} \in \text{Open}(S^2)$ (complements of closed maps)

Cl₂ η_{\pm} are continuous.

[2] The transition map is defined on the overlap $U_+ \cap U_-$.
 It is given by $\eta_+ \circ \eta_-^{-1}: \eta_-(U_+ \cap U_-) \rightarrow \eta_+(U_+ \cap U_-)$

Note $\eta_{\pm}(U_+ \cap U_-) \cong \mathbb{R}^2 \setminus \{0\}$.

$\eta_-^{-1}: \mathbb{R}^2 \setminus \{0\} \rightarrow U_+ \cap U_-$ is given by

$$x \mapsto (1 + \|x\|^2)^{-1} (2x_1 e_1 + 2x_2 e_2 + (-1 + \|x\|^2) e_3)$$

Indeed, $\frac{4x_1^2 + 4x_2^2 + 1 - 2\|x\|^2 + \|x\|^4}{1 + 2\|x\|^2 + \|x\|^4} = 1 \checkmark \Rightarrow \eta_-^{-1}(x) \in S^2 \checkmark$

$$(\eta_+ \circ \eta_-^{-1})(x) = \frac{1}{1 + \frac{-1 + \|x\|^2}{1 + \|x\|^2}} \left(\frac{2x_1}{1 + \|x\|^2} e_1 + \frac{2x_2}{1 + \|x\|^2} e_2 \right) = x \checkmark$$

$$\frac{1 + \|x\|^2}{1 + \|x\|^2 + 1 - \|x\|^2}$$

Similarly $(\eta_- \circ \eta_+)(x) = x \quad \forall x \in U_+ \cap U_-$

$$\text{Then } (\eta_+ \circ \eta_-^{-1})(x) = \frac{1}{1 + \frac{-1 + \|x\|^2}{1 + \|x\|^2}} \left(\frac{2x_1}{1 + \|x\|^2} e_1 + \frac{2x_2}{1 + \|x\|^2} e_2 \right)$$

$$\frac{1 + \|x\|^2}{1 + \|x\|^2 + 1 - \|x\|^2}$$

$$= \|x\|^{-2} x$$

Q.E.D. $\eta_+ \circ \eta_-^{-1}: \mathbb{R}^2 \setminus \{0\} \rightarrow \mathbb{R}^2 \setminus \{0\}$ is smooth.

$f: \mathbb{R}^3 \rightarrow \mathbb{R}$ given by $f(x) := \|x\|^2 - 1$ [3]

Def: $x \in \mathbb{R}^3$ is a regular point of f iff $(df)_x: T_x \mathbb{R}^3 \rightarrow T_x \mathbb{R}$ is surjective.

Def: $x \in \mathbb{R}$ is a regular value of f iff $\forall y \in f^{-1}(\{x\})$, y is a regular point of f .

Cl: 0 is a regular value of f .

Pf: $f^{-1}(\{0\}) = S^2$

$(df)_x = (D_x f) = 2x$

Of course $2x: T_x \mathbb{R}^3 \rightarrow T_x \mathbb{R}$ is surjective.
 $\cong \mathbb{R}^3 \quad \cong \mathbb{R}$

Cl: If $f: M \rightarrow N$ is smooth and $x \in N$ is a regular value of f , then $f^{-1}(\{x\})$ is a submanifold of M of dimension $m-n$.

$\Rightarrow S^2$ is a submanifold of \mathbb{R}^3 with dimension 2.

4

Q2

Tensors

10

a) Cl. $\{v_1 \otimes v_2 \in V \otimes V\} \neq V \otimes V$

Pf. Let $T \in V \otimes V$ be given of rank 2 or higher.

Let $\{e_i\}_i$ be an ONB for V .

Then $T = T_{ij} e_i \otimes e_j \quad \exists \{T_{ij}\}_{i,j} \subseteq \text{field}(V)$.

Assume $\exists (v_1, v_2) \in V^2 : T = v_1 \otimes v_2$.

Then $T = v_1 \otimes v_2 = (v_1)_i e_i \otimes (v_2)_j e_j = (v_1)_i (v_2)_j e_i \otimes e_j$

$\Rightarrow T_{ij} = (v_1)_i (v_2)_j$

$\Rightarrow T_{ij} e_j = (v_1)_i (v_2)_j e_j = (v_1)_i v_2$

\Rightarrow Every i^{th} row of the matrix T , $T_{ij} e_j$, is a multiple of v_2 , so T has rank 1. $\Rightarrow \square$

b) Cl. $V \otimes W^* \cong \underbrace{\mathcal{L}(W, V)}_{\text{lin. maps } W \rightarrow V}$ as vsp. isomorphism.

Pf. Define $\eta: V \otimes W^* \rightarrow \mathcal{L}(W, V)$ by:

Let $T \in V \otimes W^*$ be given. Then $T = \sum_j v_j \otimes \varphi_j^*$
for $\{v_j\}_j \subseteq V$, $\{\varphi_j^*\}_j \subseteq W^*$.

Let $w \in W$ be given. Then $\sum_j v_j \otimes \underbrace{\varphi_j^*(w)}_{\in \text{Field}(W)} \in V$

$\Rightarrow \eta(T) := \sum_j \varphi_j^*(\cdot) v_j$