Integrable delay-differential equations

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Overview

- Delay (or differential-delay) equations arise in many important applications.
- Several differential-delay equations have been obtained as similarity reductions of integrable equations.
- In 1992, Quispel, Capel and Sahadevan obtained the equation

$$w(z)[w(z+1) - w(z-1)] = aw(z) + bw'(z).$$

- Delay equations from Bäcklund transformations of Painlevé equations.
- How can we find more examples of such equations?
- Is there an analogue of the QRT system?

Some delay Painlevé equations in the literature

• Quispel, Capel and Sahadevan (1992) obtained the equation

$$au(z) + bu'(z) = u(z) [u(z+1) - u(z-1)]$$

as a symmetry reduction of the Manakov/Kac-van Moebeke equation.

- Grammaticos, Ramani and Moreira (1993) studied singularity confinement for delay equations of bi-Riccati-type.
- Levi and Winternitz (2007) considered symmetry reductions of Toda.
- Joshi (2009) used a direct method to find the following reduction of Toda:

$$au(z) + u'(z) = u(z) [v(z+1) - v(z)],$$

 $av(z) + v'(z) = 2 [u(z)^2 - v(z-1)^2] + c,$

• Fedorov, Gordoa and Pickering (2014) considered hierarchies of delay equations.

Two types of delay equations

• Equations for which we can solve for the highest/lowest shift, e.g.,

$$A(u, u')u(z + 1)u(z - 1) + B(u, u')u(z + 1) + C(u, u')u(z - 1) + D(u, u') = 0,$$

where $u \equiv u(z)$.

- Standard confinement-type arguments can be applied to these equations.
- Bi-Riccati:

$$\mathbf{U}(z)^t \mathbf{A} \mathbf{U}(z+1) = 0,$$

where $\mathbf{U} = (u' \ u^2 \ u \ 1)^t$ and \mathbf{A} is a constant 4×4 matrix.

Analogues of constants and periodic functions

Consider the constant coefficient homogeneous differential-delay equation

$$u(z+1) - u(z) + ku'(z) = 0. (1)$$

We see that $u(z) = e^{\lambda z}$ is a solution if and only if $e^{\lambda} - 1 + k\lambda = 0$. This characteristic equation has a countable infinity of solutions λ_n , $n \in \mathbb{Z}$. So for suitable constants c_n , equation (1) has the solution

$$u(z) = \sum_{n = -\infty}^{\infty} c_n \exp(\lambda_n z). \tag{2}$$

Note that when k = 0, we can index the λ_n 's such that $\lambda_n = 2\pi i n$ and the expansion (2) becomes the Fourier series of the period one function u.

Discrete Painlevé equations as Bäcklund transformations

- This example is from Fokas, Grammaticos and Ramani.
- The third Painlevé equation with $\gamma = 0, \delta = -\alpha = 1$ is

$$w'' = \frac{w'^2}{w} - \frac{w'}{x} - \frac{1}{x}(w^2 - \beta) - \frac{1}{w},\tag{3}$$

where β is a parameter.

• If $\mathbf{w} \equiv \mathbf{w}(\mathbf{x}, \boldsymbol{\beta})$ is a solution of equation (3) then

$$w(x; \beta + 2) = \frac{x(1 + w'(x; \beta))}{w(x; \beta)^2} - \frac{\beta + 1}{w(x; \beta)}, \text{ and}$$

$$w(x; \beta - 2) = \frac{x(1 - w'(x; \beta))}{w(x; \beta)^2} - \frac{\beta - 1}{w(x; \beta)},$$
(5)

$$w(x;\beta-2) = \frac{x(1-w'(x;\beta))}{w(x;\beta)^2} - \frac{\beta-1}{w(x;\beta)},\tag{5}$$

are also solutions with β replaced by $\beta + 2$ and $\beta - 2$ respectively.

• Adding equations (4) and (5) gives

$$w(x; \beta + 2) + w(x; \beta - 2) = \frac{2x}{w(x; \beta)^2} - \frac{2\beta}{w(x; \beta)}.$$

Delay Painlevé equations from Bäcklund transformations

• Two BTs for P_{III} (with $\gamma = 0, \delta = -\alpha = 1$) are

$$w(x; \beta + 2) = \frac{x(1 + w_x(x; \beta))}{w(x; \beta)^2} - \frac{\beta + 1}{w(x; \beta)}, \text{ and}$$
 (6)

$$w(x;\beta-2) = \frac{x(1-w_x(x;\beta))}{w(x;\beta)^2} - \frac{\beta-1}{w(x;\beta)}.$$
 (7)

• Taking the difference (6)-(7) gives

$$w(x; \beta + 2) - w(x; \beta - 2) = \frac{2xw_x(x; \beta)}{w(x; \beta)^2} - \frac{2}{w(x; \beta)}.$$

• The reduction $w(x; \beta) = u(z)$, where $z = (\beta/2) + \ln x$ gives

$$u(z+1) - u(z-1) = \frac{2\{u'(z) - u(z)\}}{u(z)^2},$$

which has a continuum limit to P_I.

Bi-Riccati delay Painlevé equations from BTs

• Shifting $\beta \mapsto \beta + 2$ in the second BTs gives the pair

$$w(x;\beta)w(x;\beta+2) = \frac{x(1+w_x(x;\beta))}{w(x;\beta)} - (\beta+1), \text{ and}$$
 (8)

$$w(x; \beta + 2)w(x; \beta) = \frac{x(1 - w_x(x; \beta + 2))}{w(x; \beta + 2)} - (\beta + 1).$$
 (9)

• Taking the difference (8)–(9) gives

$$[w(x; \beta)w(x; \beta + 2)]_x + w(x; \beta + 2) - w(x; \beta) = 0.$$

- The reduction $w(x;\beta) = \frac{b}{2}xu(z)$, where $z = \frac{\beta h}{2} + \frac{2a}{b}\ln x$ gives a[u(z)u(z+h)]' + bu(z)u(z+h) + u(z+h) u(z) = 0.
- Writing $u(z) = \frac{h^3}{2a}v(z) \frac{h}{2a}$ and $b/a = \frac{3}{2}h^4 + O(h^5)$, then in the limit $h \to 0$ we recover P_I .

Another bi-Riccati delay Painlevé equation from BTs

• For P_{III} with $\gamma = -\delta = 1$, we have the BTs

$$w(x; -\alpha, -\beta) = -w(x; \alpha, \beta),$$

$$w(x; -\beta, -\alpha) = w(x; \alpha, \beta)^{-1},$$

$$w(x; -\beta - 2, -\alpha - 2) = w(x; \alpha, \beta) \left[1 + \frac{2 + \alpha + \beta}{x \left(\frac{w_x}{w} + w + \frac{1}{w} \right) - 1 - \beta} \right].$$

• Using these transformations we obtain the equation

$$\frac{w_x(x;\alpha+2,\beta+2)}{w(x;\alpha+2,\beta+2)} + \frac{w_x(x;\alpha,\beta)}{w(x;\alpha,\beta)}$$

$$= \left(w(x;\alpha+2,\beta+2) + \frac{1}{w(x;\alpha+2,\beta+2)}\right) - \left(w(x;\alpha,\beta) + \frac{1}{w(x;\alpha,\beta)}\right).$$

• The reduction $w(x;\beta) = u(z)$, where $z = \frac{(\alpha+\beta)h}{4} - kx$ gives

$$k[u(z)u(z+h)]' + [u(z+h)u(z) - 1][u(z+h) - u(z)] = 0.$$

Addition laws for elliptic functions

Recall that the Weierstrass \wp function satisfies

$$\wp'(z; g_2, g_3) = 4\wp(z; g_2, g_3)^3 - g_2\wp(z; g_2, g_3) - g_3,$$

(where "'" denotes the derivative with respect to the first argument) and the addition law

$$\wp(z \pm h; g_2, g_3) = \frac{1}{4} \left\{ \frac{\wp'(z; g_2, g_3) \mp \wp'(h; g_2, g_3)}{\wp(z; g_2, g_3) - \wp(h; g_2, g_3)} \right\}^2 - \wp(z; g_2, g_3) - \wp(h; g_2, g_3).$$

It is straightforward to verify that

$$u(z) = \sqrt{\frac{\wp(h; g_2, g_3)}{h}} \{ \wp(hz + c; g_2, g_3) - \wp(h; g_2, g_3) \}$$

satisfies

$$u(z)^{2} \{u(z+1) - u(z-1)\} = u'(z)$$
(10)

for arbitrary c, h, g_2 and g_3 .

The symmetric QRT map

The symmetric Quispel-Roberts-Thompson map is

$$x_{n+1} = \frac{f_1(x_n) - x_{n-1}f_2(x_n)}{f_2(x_n) - x_{n-1}f_3(x_n)},$$

where

$$\begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix} = (\mathbf{A}_0 \mathbf{X}_n) \times (\mathbf{A}_1 \mathbf{X}_n), \quad \mathbf{X}_n = \begin{pmatrix} x_n^2 \\ x_n \\ 1 \end{pmatrix}, \quad \mathbf{A}_j = \begin{pmatrix} \alpha_j, \ \beta_j, \ \gamma_j \\ \beta_j \ \epsilon_j \ \zeta_j \\ \gamma_j \ \zeta_j \ \mu_j \end{pmatrix}, \quad j = 0, 1.$$

This system has the conserved quantity $K = \frac{\mathbf{X}_n^T \mathbf{A}_0 \mathbf{X}_{n+1}}{\mathbf{X}_n^T \mathbf{A}_1 \mathbf{X}_{n+1}}$.

Analogues of QRT mappings (with Bjorn Berntson)

An analogue of symmetric QRT mappings are those differential-delay equations of the form

$$A(u, u')u(z+1)u(z-1) + B(u, u')u(z+1) + C(u, u')u(z-1) + D(u, u') = 0,$$

where $u \equiv u(z)$, that possess at least a two-parameter solution given in terms of elliptic functions. For example

$$(1 - u(z)^2) \{u(z+1) - u(z-1)\} = bu'(z),$$

where b is a constant. This has a two-parameter family of solutions in terms of the Jacobi sn function because of the identity

$$\operatorname{sn}(z \pm h; k) = \frac{\operatorname{sn}(z; k) \operatorname{sn}'(h; k) \pm \operatorname{sn}'(z; k) \operatorname{sn}(h; k)}{1 - k^2 \operatorname{sn}(z; k)^2 \operatorname{sn}(h; k)^2},$$

where "'" denotes the derivative with respect to the first argument.

Bi-Riccati analogues of QRT mappings

• We wish to identify equations of the form

$$\mathbf{W}^{\mathrm{T}}(z+h)K\mathbf{W}(z) = 0$$
, where $\mathbf{W}(z) = \begin{pmatrix} 1 \\ w(z) \\ w^2(z) \\ w'(z) \end{pmatrix}$,

admitting a two-parameter (ϵ and z_0) family of solutions of the form

$$w(z) = \frac{\alpha(\epsilon)\operatorname{sn}(\Omega(\epsilon)[z-z_0]; k(\epsilon)) + \beta(\epsilon)}{\gamma(\epsilon)\operatorname{sn}(\Omega(\epsilon)[z-z_0]; k(\epsilon)) + \delta(\epsilon)}.$$

• Ignoring the z_0 dependence, we look for solutions of the form

$$w(z) = \frac{\alpha \operatorname{sn}(\Omega z; k) + \beta}{\gamma \operatorname{sn}(\Omega z; k) + \delta}.$$

A simpler problem

The vector

$$\mathbf{U}(z) = egin{pmatrix} 1 \\ u(z) \\ u^2(z) \\ u'(z) \end{pmatrix},$$

where

$$u(z) = \operatorname{sn}(\Omega z; k),$$

solves the equation

$$\mathbf{U}(z+h)^{\mathrm{T}}\mathbf{X}\mathbf{U}(z) = 0$$

if and only if X has the form

$$\mathbf{X} = \sum_{j=0}^{7} \lambda_j X_j,$$

where $\lambda_0, \ldots, \lambda_7$ are constants and the X_j s have specific forms.

where $s = \operatorname{sn}(\Omega h; k)$, $c = \operatorname{cn}(\Omega h; k)$ etc.

Bi-Riccati QRT-type equations

• Consider the equation $\mathbf{U}(z+h)^{\mathrm{T}}\mathbf{X}\mathbf{U}(z)=0$ with $u(z)=\mathrm{sn}(\Omega z;k)$ and

$$\mathbf{X} = \sum_{j=0}^{7} \lambda_j X_j.$$

• The transformation

$$w(z) = \frac{\alpha u(z) + \beta}{\gamma u(z) + \delta}, \qquad \alpha \delta - \beta \gamma \neq 0$$

induces the transformation

$$\hat{X} = M^{\mathrm{T}} X M,$$

where

$$M = \begin{pmatrix} \delta^2 & 2\gamma\delta & \gamma^2 & 0\\ \beta\delta & \alpha\delta + \beta\gamma & \alpha\gamma & 0\\ \beta^2 & 2\alpha\beta & \alpha^2 & 0\\ 0 & 0 & 0 & \alpha\delta - \beta\gamma \end{pmatrix}.$$

• In this way we obtain a number of delay-differential equations with multi-parameter families of elliptic function solutions. No geometric picture yet like QRT.

First-Order Difference Equations

• Consider the difference equation

$$y(z+1) = R(y(z)). \tag{11}$$

- If R is rational then equation (11) admits a non-constant meromorphic solution.
- If R is polynomial then equation (11) admits a non-constant entire solution.
- An immediate consequence of this theorem is that the Logistic map,

$$y(z+1) = \alpha y(z)(1 - y(z)),$$

has a non-constant entire solution, y(z) = w(z).

• The logistic map has a family of entire solutions:

$$y(z) = w(z - p(z))$$
, where p is periodic.

• Nevanlinna theory provides a concept of "nice" meromorphic functions: functions of finite order.

Nevanlinna Theory

- Nevanlinna characteristic T(r, f).
- \bullet For an entire function f,

$$T(r, f) \sim \log M(r, f), \quad M(r, f) = \max_{|z|=r} |f(z)|.$$

 \bullet More generally, for a meromorphic function f,

$$T(r, f) = m(r, f) + N(r, f),$$

where m(r, f) is a measure of how large f is on |z| = r and N(r, f) is a measure of how many poles f has in $D_r := \{z : |z| \le r\}$.

- The order of f is $\rho(f) = \limsup_{r \to \infty} \frac{\log(T(r, f))}{\log r}$.
- The hyper-order of f is $\rho_2(f) = \limsup_{r \to \infty} \frac{\log \log(T(r, f))}{\log r}$.
- Examples of finite-order meromorphic functions: e^z , $\cos z$, $\tan z$, $\wp(z)$.
- Infinite-order: $\exp(\exp z)$, $\exp(\cos(\sqrt{z})$.

Difference equations of Painlevé type

- (Ablowitz, H, Herbst) An analogue of the Painlevé property for difference equations is the existence of sufficiently many finite-order meromorphic solutions.
- **Theorem** (Yanagihara) If the difference equation

$$y(z+1) = R(z, y(z)),$$

where

$$R(z,y) = \frac{a_0(z) + a_1(z)y + \dots + a_p(z)y^p}{b_0(z) + b_1(z)y + \dots + b_q(z)y^q},$$

admits a finite-order non-rational meromorphic solution, then $\max(p,q) \leq 1$.

• This gives the difference Riccati equation

$$y(z+1) = \frac{\alpha(z)y(z) + \beta(z)}{\gamma(z)y(z) + \delta(z)},$$

which is linearized by

$$y(z) = \frac{\alpha(z-1)}{\gamma(z-1)} \left[\frac{w(z) - w(z-1)}{w(z)} \right].$$

Theorem (H. and Korhonen, 2007)

If the equation
$$\overline{w} + \underline{w} = R(z, w),$$
 (†)

has an admissible meromorphic solution of finite order, then either w satisfies the discrete Riccati eqn $\overline{w} = (\overline{p}w + q)/(w + p)$, or (†) can be transformed by a linear change of variables to one of the following equations:

$$\overline{w} + w + \underline{w} = \frac{\pi_1 z + \pi_2}{w} + \kappa_1$$

$$\overline{w} - w + \underline{w} = \frac{\pi_1 z + \pi_2}{w} + (-1)^z \kappa_1$$

$$\overline{w} + \underline{w} = \frac{\pi_1 z + \pi_3}{w} + \pi_2$$

$$\overline{w} + \underline{w} = \frac{\pi_1 z + \kappa_1}{w} + \frac{\pi_2}{w^2}$$

$$\overline{w} + \underline{w} = \frac{(\pi_1 z + \kappa_1)w + \pi_2}{(-1)^{-z} - w^2}$$

$$\overline{w} + \underline{w} = \frac{(\pi_1 z + \kappa_1)w + \pi_2}{1 - w^2}$$

$$\overline{w} + w = p$$

$$\overline{w} + w = p$$

$$\overline{w} + w = p$$

where p, q, π_k, κ_k are "small" functions and π_k and κ_k are periodic with period k.

Delay equations admitting meromorphic solutions with $\rho_2(w) < 1$ (with Risto Korhonen 2017)

• Let w be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) + a(z)\frac{w'(z)}{w(z)} = R(z, w(z)),$$

where R is rational in both its arguments and a is a rational function of z, such that $\rho_2(w) < 1$.

Then $\operatorname{Deg}_w R(z, w) \leq 4$.

- Suppose furthermore that R(z, w) = P(z, w)/Q(z, w), where $Q(z, 0) \not\equiv 0$. Then either
 - 1. $\text{Deg}_w P(z, w) = 1 + \text{Deg}_w Q(z, w) \le 3$

or

$$2. \frac{P(z,w)}{Q(z,w)} = \frac{\alpha(z)w(z) + \beta(z)}{\gamma(z)w + \delta(z)}.$$

Delay equations with meromorphic solutions with hyper-order < 1: $\deg_w R(z,w) = 0$

• Let w(z) be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) + a(z)\frac{w'(z)}{w(z)} = b(z),$$

where $a(z) \not\equiv 0$ and b(z) are rational. If the hyper-order of w(z) is less than one and w has "a lot of simple zeros" then the coefficients a(z) and b(z) are both constants.

• Note that for any rational a(z), if $b(z) \equiv p\pi i a(z)$, where $p \in \mathbb{N}$, then

$$w(z) = C \exp(p\pi i z), \qquad C \neq 0,$$

is a zero-free entire transcendental finite-order solution.

• Here "a lot of simple zeros" means that for any $\epsilon > 0$,

$$\overline{N}\left(r,\frac{1}{w}\right) \ge \left(\frac{3}{4} + \epsilon\right)T(r,w) + S(r,w).$$

A non-autonomous equation

Theorem

• Let w(z) be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) = \frac{a(z)w'(z) + b(z)w(z)}{w(z)^2} + c(z),$$

where $a(z) \not\equiv 0$, b(z) and c(z) are rational.

• If the hyper-order of w(z) is less than one and "w(z) has a lot of zeros" then the equation takes the form

$$w(z+1) - w(z-1) = \frac{(\lambda + \mu z)w'(z) + (\nu\lambda + \mu(\nu z - 1))w(z)}{w(z)^2},$$

where λ , μ and ν are constants.

Singularity confinement

Grammaticos, Ramani and Papageorgiou (1991);

Ramani, Grammaticos and Hietarinta (1991)

$$y_{n+1} + y_{n-1} = \frac{a_n + b_n y_n}{1 - y_n^2}$$

$$y_{n-1} = k,$$

$$y_n = \theta + \epsilon, \qquad \theta = \pm 1$$

$$y_{n+1} = -\frac{a_n + \theta b_n}{2\theta} \epsilon^{-1} + O(1),$$

$$y_{n+2} = -\theta + \frac{2\theta b_{n+1} - \theta b_n - a_n}{a_n + \theta b_n} \epsilon + O(\epsilon^2),$$

$$y_{n+3} = \frac{a_n + \theta b_n}{2\theta} \left\{ \frac{(a_{n+2} - a_n) - \theta(b_{n+2} - 2b_{n+1} + b_n)}{\theta(2b_{n+1} - b_n) - a_n} \right\} \epsilon^{-1} + O(1).$$

Confinement:

$$y_{n+1} + y_{n-1} = \frac{\alpha + \beta(-1)^n + (\gamma n + \delta)y_n}{1 - y_n^2}$$

Example of Hietarinta and Viallet

$$y_{n+1} + y_{n-1} = y_n + \frac{a}{y_n^2}$$

$$y_{n-1} = k + o(1),$$

 $y_n = \epsilon,$
 $y_{n+1} = \epsilon^{-2} - k + \epsilon + O(\epsilon^2),$
 $y_{n+2} = \epsilon^{-2} - k + \epsilon^4 + O(\epsilon^5),$
 $y_{n+3} = -\epsilon + 2\epsilon^4 + O(\epsilon^5),$
 $y_{n+4} = k + o(1).$

Exact calculations of degree growth

There are two equivalent definitions of the degree of a rational function.

Let $R(z) = \frac{P(z)}{Q(z)}$, where P and Q are polynomials with no common factors. Then

- $1. \deg(R) = \max\{\deg(P(z)), \deg(Q(z))\}.$
- 2. Let a be any number in the extended complex plane $\mathbb{CP}^1 = \mathbb{C} \cup \{\infty\}$. Then the $\deg(R)$ is the number of pre-images of a in \mathbb{CP}^1 counting multiplicities.

For example, the degree of the rational function

$$\frac{2x^5 - 4x^4 + 2x^3 + x + 1}{x(x-1)^2} = \frac{x+1}{x(x-1)^2} + 2x^2$$

is 5.

Singularity confinement revisited

$$y_{n+1} + y_{n-1} = \frac{a_n + b_n y_n}{1 - y_n^2}$$

$$y_{n-1} = k + o(1),$$

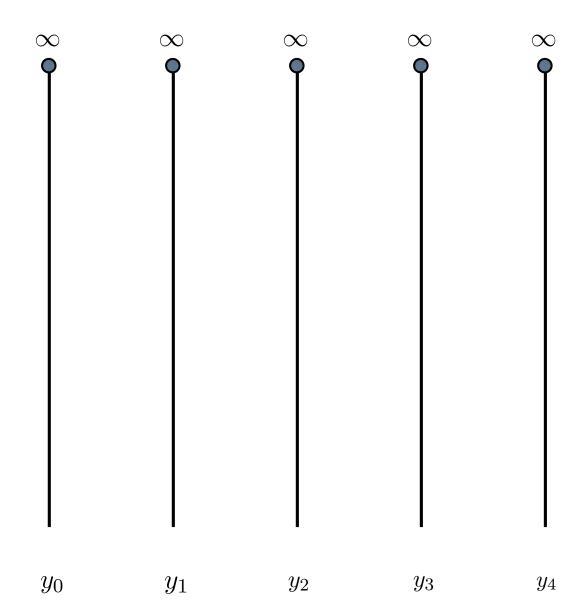
$$y_n = \theta + \epsilon, \quad \theta = \pm 1, \quad \epsilon = (z - z_0)^p f(z), \quad f \text{ analytic at } z_0, \quad f(z_0) \neq 0$$

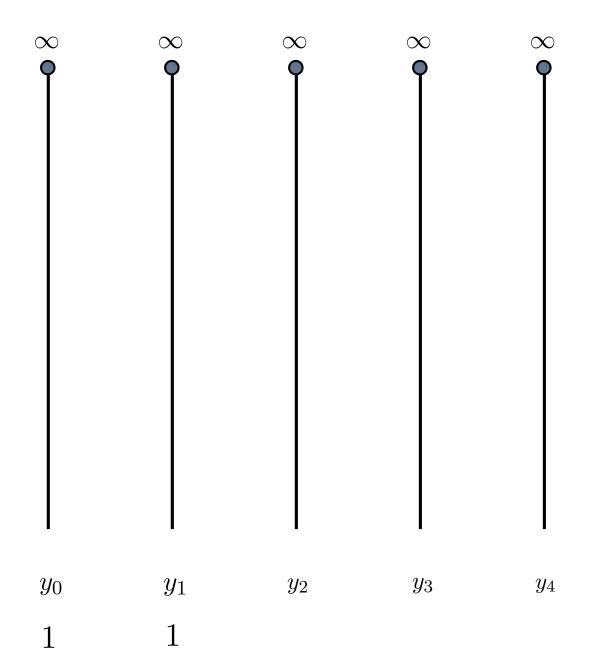
$$y_{n+1} = -\frac{a_n + \theta b_n}{2\theta} \epsilon^{-1} + O(1),$$

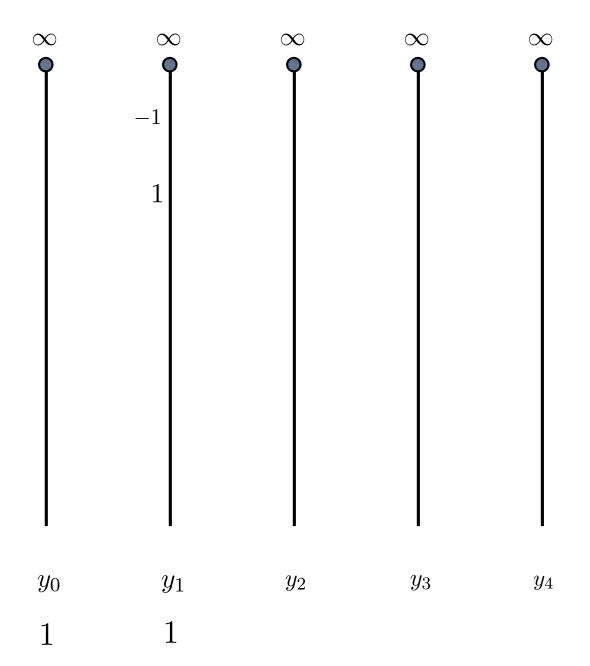
$$y_{n+2} = -\theta + \frac{2\theta b_{n+1} - \theta b_n - a_n}{a_n + \theta b_n} \epsilon + O(\epsilon^2),$$

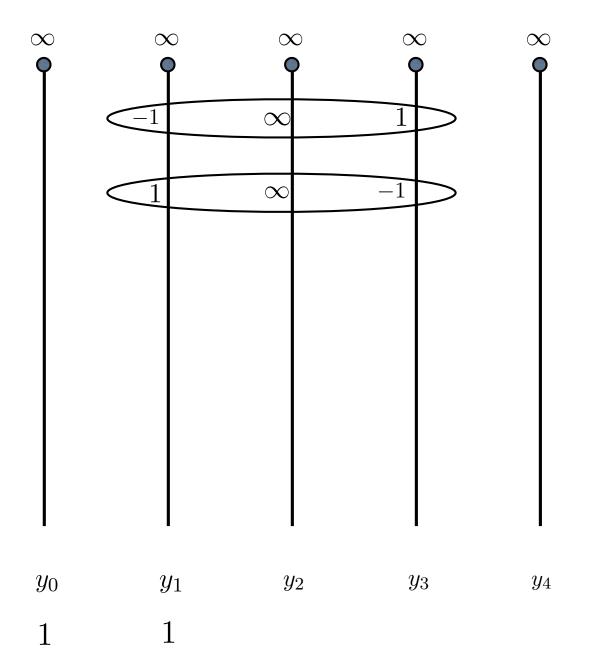
$$y_{n+3} = \frac{a_n + \theta b_n}{2\theta} \left\{ \frac{(a_{n+2} - a_n) - \theta(b_{n+2} - 2b_{n+1} + b_n)}{\theta(2b_{n+1} - b_n) - a_n} \right\} \epsilon^{-1} + O(1).$$

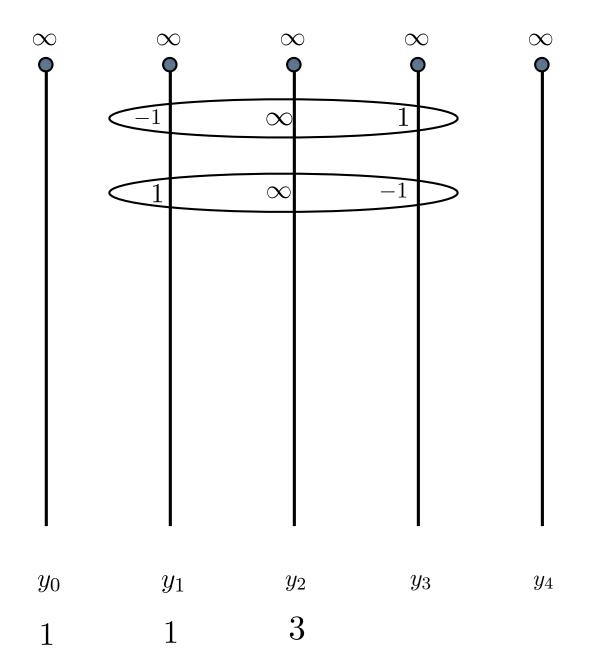
Also, if $y_{n-1} \sim \alpha z$ and $y_n \sim \beta z$ as $z \to \infty$, then $y_{n+1} \sim -\alpha z$. Take $y_0 = Az + B$ and $y_1 = Cz + D$, $AC \neq 0$.

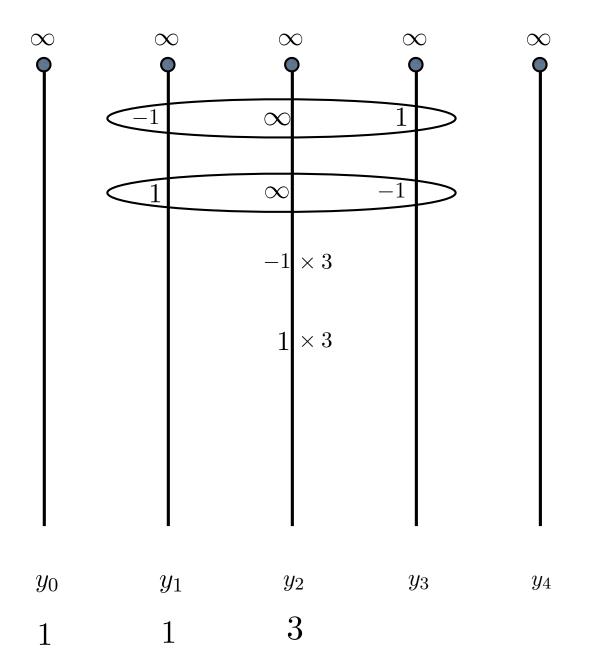


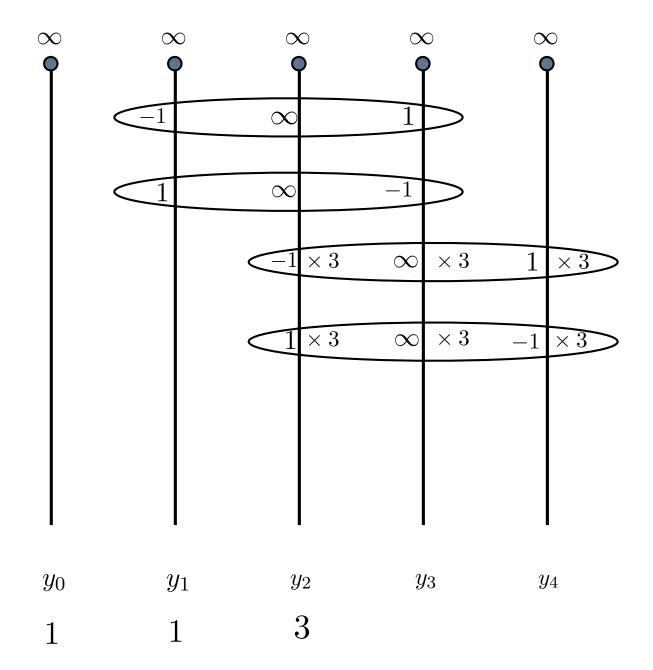


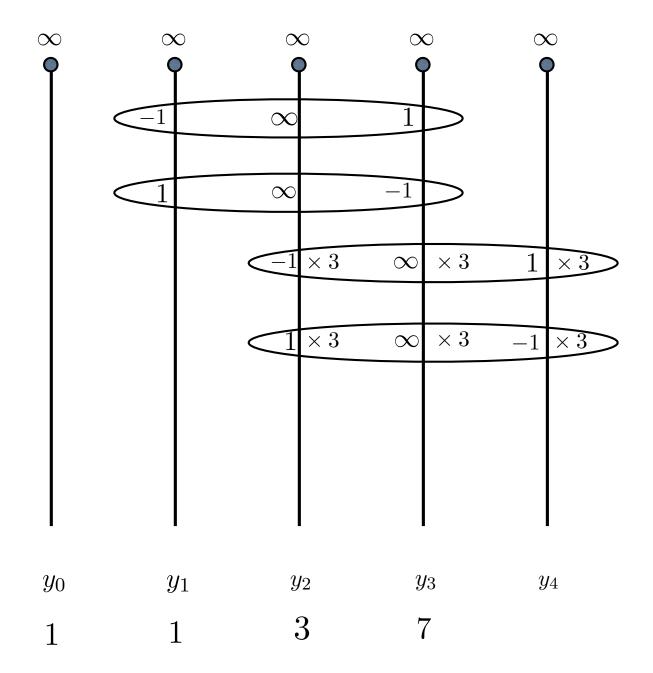


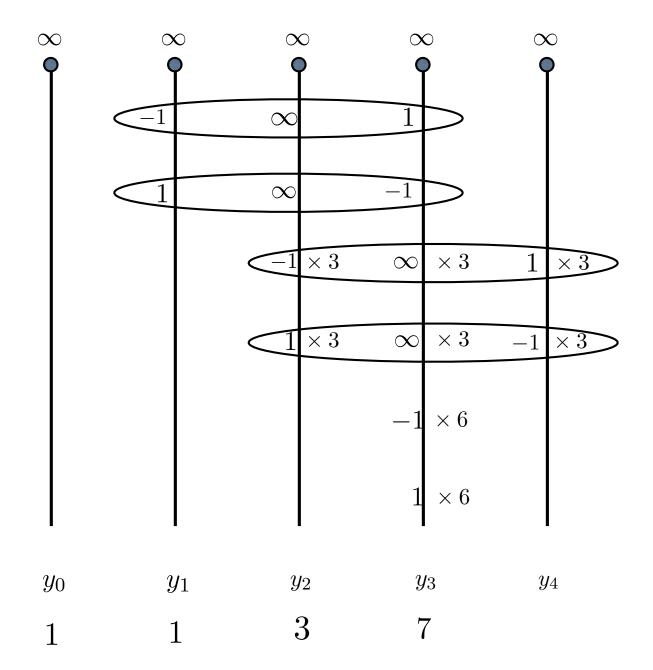


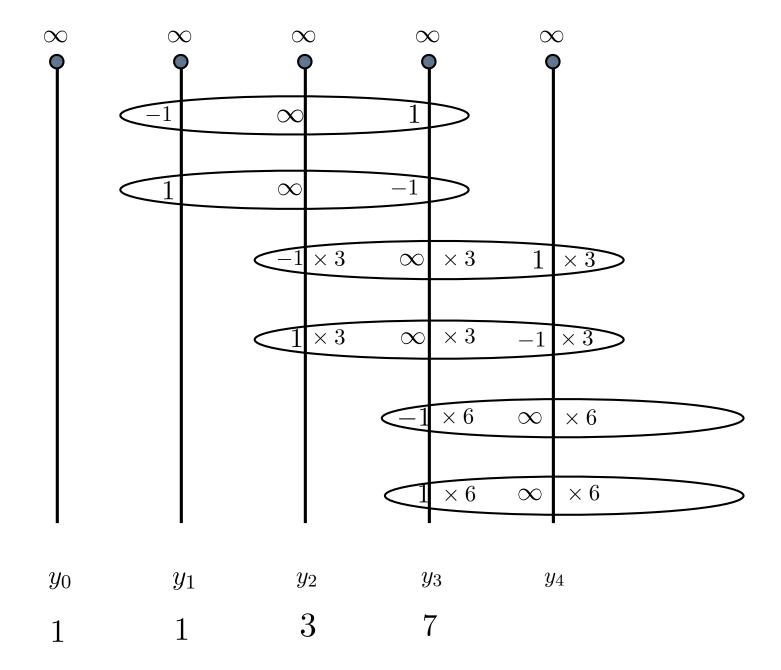


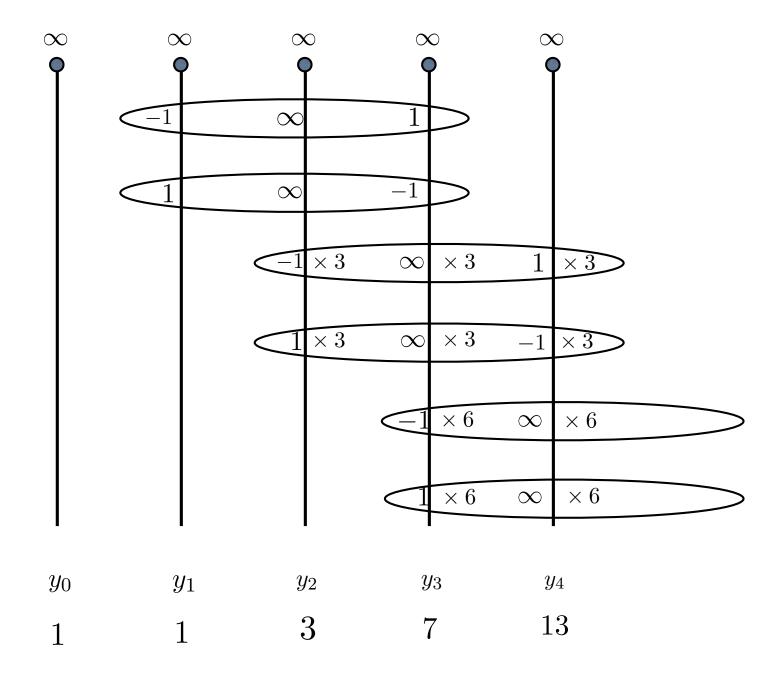


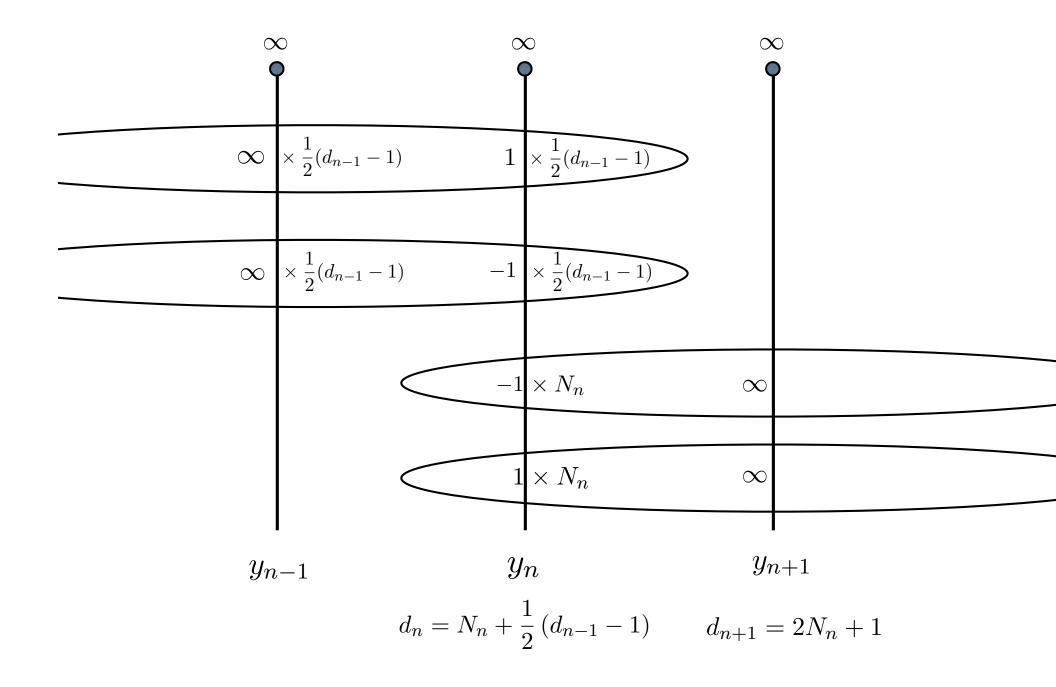












Exact formula for degrees

We have

$$d_{n+1} = 2N_n + 1$$
 and $d_n = N_n + \frac{1}{2}(d_{n-1} - 1)$.

Eliminating N_n gives

$$d_{n+1} - 2d_n + d_{n-1} = 2.$$

We also have the initial conditions $d_0 = d_1 = 1$. Hence

$$d_n = n(n-1) + 1.$$

Example of Hietarinta and Viallet revisited

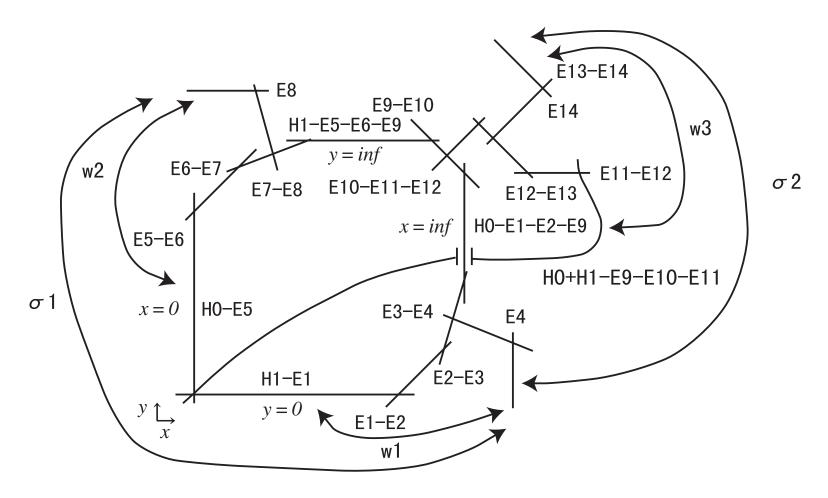
$$y_{n+1} + y_{n-1} = y_n + \frac{a}{y_n^2}$$

$$y_{n-1} = k + o(1),$$

 $y_n = \epsilon,$
 $y_{n+1} = \epsilon^{-2} - k + \epsilon + O(\epsilon^2),$
 $y_{n+2} = \epsilon^{-2} - k + \epsilon^4 + O(\epsilon^5),$
 $y_{n+3} = -\epsilon + 2\epsilon^4 + O(\epsilon^5),$
 $y_{n+4} = k + o(1).$

We will choose $y_0 \sim \alpha z + \beta$ and $y_1 \sim \gamma z + \delta$ as $z \to \infty$, where $\alpha \gamma (\alpha - \gamma) \neq 0$. Then y_n has a simple pole at $z = \infty$ for all n.

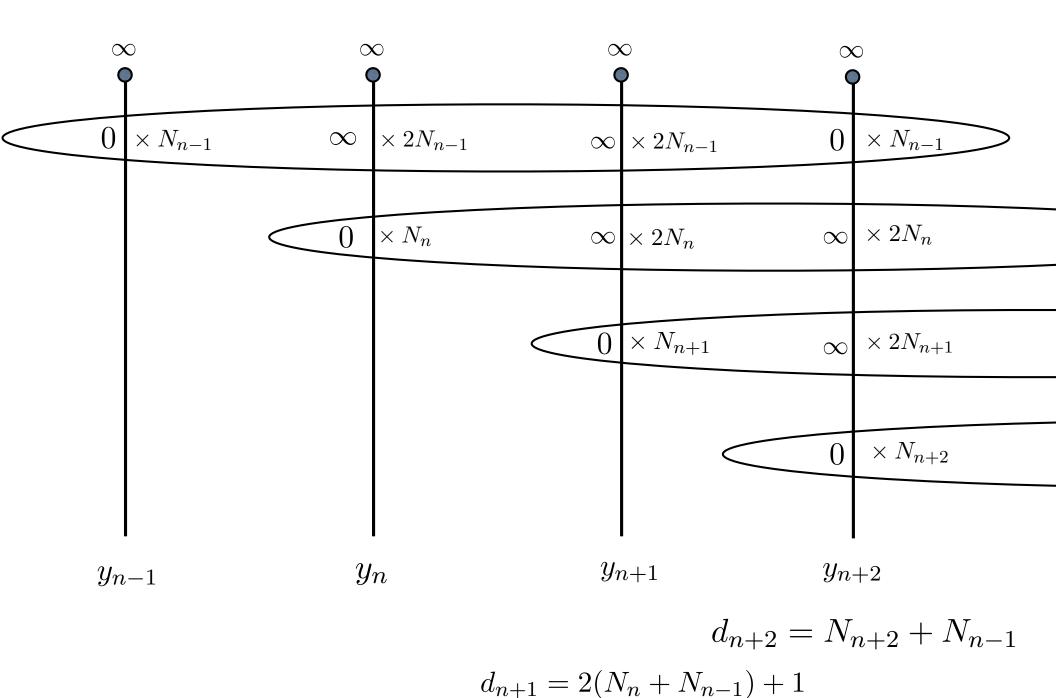
Takenawa's sequence of blow-ups for the Hietarinta-Viallet equation



He provided a rigorous proof that the algebraic entropy is

$$\frac{3+\sqrt{5}}{2}$$

This value had been calculated using more heuristic methods by Hietarinta and Viallet.



Substituting

$$N_n + N_{n-1} = (d_{n+1} - 1)/2$$
 and $N_{n+2} + N_{n-1} = d_{n+2}$

in

$$(N_n + N_{n-1}) - (N_n + N_{n-3}) + (N_{n-2} + N_{n-3}) - (N_{n-1} + N_{n-2}) = 0$$

gives

$$d_{n+1} - 3d_n + d_{n-1} = 1.$$

Together with the initial conditions $d_0 = d_1 = 1$, this gives

$$d_n = \frac{\sqrt{5} - 1}{\sqrt{5}} \left(\frac{3 + \sqrt{5}}{2} \right)^n + \frac{\sqrt{5} + 1}{\sqrt{5}} \left(\frac{3 - \sqrt{5}}{2} \right)^n - 1.$$

It follows that the algebraic entropy is

$$\frac{3+\sqrt{5}}{2}.$$

Singularity confinement, discrete integrability and delay-differential equations

- Some form of singularity confinement underlies most "detectors" of integrability for discrete systems (rational surfaces approach, algebraic entropy, Nevanlinna theory, Diophantine integrability)
- Singularity (non-)confinement-type calculations underlie the more precise results from Nevanlinna theory for delay differential equations.
- Alex Stokes studied the way that singularity patterns vary with the multiplicity with which a solution hits singular values.
- \bullet In particular he observed that if a solution u of

$$au(z) + bu'(z) = u(z) [u(z+1) - u(z-1)]$$

is regular at $z = z_0 - 1$ and vanishes at $z = z_0$ with multiplicity m, then u has simple poles at $z_0 + 1, \ldots z_0 + 2m$, vanishes again at $z_0 + 2m + 1$ with multiplicity m and is neither 0 nor ∞ at $z = z_0 + 2m + 2$.

Delay equations with meromorphic solutions with hyper-order < 1 (with Risto Korhonen and Jun Wang — 2022)

Theorem Let w be a transcendental meromorphic solution of

$$w(z+1) - w(z-1) + a(z)\frac{w'(z)}{w(z)} = \frac{P(z,w)}{Q(z,w)}, \quad (*)$$

where a is a rational function of z, P(z, w) and Q(z, w) are co-prime polynomials in w with rational coefficients in z. If $\rho_2(w) < 1$, then R(z, w) = P(z, w)/Q(z, w) satisfies one of the following conditions

- $1. \deg_w(R) \le 1;$
- 2. $\deg_w(P) = \deg_w(Q) + 1 \le 3$ and w = 0 is at most a simple root of Q;
- 3. $Q(z, w) = w\tilde{Q}(z, w)$, where $\tilde{Q}(z, 0) \not\equiv 0$ and either $\deg_w(P) = \deg_w(\tilde{Q}) + 2 = 4$ or $\deg_w(P) \leq 2$ and $\deg_w(Q) \leq 1$.

Delay equations with meromorphic solutions with hyper-order < 1: $\deg_w R(z,w) = 1$

• Let w(z) be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) + a(z)\frac{w'(z)}{w(z)} = \frac{\alpha(z)w(z) + \beta(z)}{w(z) - b(z)},$$

where $a \not\equiv 0$, $b \not\equiv 0$, α and β are rational functions of z and $\alpha \neq -\beta/b$. If the hyperorder of w(z) is less than one then "w has very few zeros, ignoring multiplicities":

$$\bar{N}\left(r, \frac{1}{w}\right) = S(r, w)$$

and

$$a(z+1)\left[a'(z+2) + b(z+3) - \alpha(z+2)\right] + a(z+2)\left[a'(z+1) + b(z) - \alpha(z+1)\right] = 0.$$

• In particular, if the equation is autonomous or if N(r, 1/w) = S(r, w), then $\rho_2(w) \ge 1$.

Delay equations with meromorphic solutions with hyper-order < 1:

$$\deg_w P(z, w) = \deg_w Q(z, w) + 1 \le 3$$

Let w(z) be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) + a(z)\frac{w'(z)}{w(z)} = \frac{\alpha_3(z)w(z)^3 + \alpha_2(z)w(z)^2 + \alpha_1(z)w(z) + \alpha_0(z)}{w(z)^2 + b_1(z)w(z) + b_0(z)},$$

where $a \not\equiv 0$, $b \not\equiv 0$, α and β are rational functions of z and $w^2 + b_1 w + b_0 = 0$ has distinct non-zero roots. If the hyper-order of w(z) is less than one then w satisfies the Riccati equation

$$w' = \frac{\alpha_3(z)}{a(z)}w^2 + \frac{\alpha_0(z)}{a(z)b_0(z)}w.$$

Delay equations with meromorphic solutions with hyper-order < 1:

$$\deg_w P(z, w) = \deg_w \tilde{Q}(z, w) + 2 \le 3$$

• Let w(z) be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) + a(z)\frac{w'(z)}{w(z)} = \frac{\alpha_2(z)w(z)^2 + \alpha_1(z)w(z) + \alpha_0(z)}{w(z)[w(z) - b(z)]},$$

where $a \not\equiv 0$, $b \not\equiv 0$, α_0 and α_1 are rational functions of z and $\alpha_2 b^2 + \alpha_1 b + \alpha_0 \not\equiv 0$. If the hyper-order of w(z) is less than one, then w has "a lot of simple zeros":

$$N\left(r, \frac{1}{w}\right) = T(r, w) + S(r, w)$$

and

$$a(z+1)\left[a'(z+2) + \alpha_2(z+2) - b(z+3)\right] = a(z+2)\left[a'(z+1) + \alpha_2(z+1) + b(z+1)\right].$$

• In particular, if the equation is autonomous, then $\rho_2(w) \geq 1$.

Delay equations with meromorphic solutions with hyper-order < 1:

$$\deg_w P(z, w) = \deg_w \tilde{Q}(z, w) + 2 = 4$$

- Here we just give an example.
- The function

$$w(z) = \tan(\pi z/4)$$

satisfies the equation

$$w(z+1) - w(z-1) + \frac{4}{\pi} \frac{w'(z)}{w(z)} = \frac{1 + 4w(z)^2 - w(z)^4}{w(z)[w(z)^2 - 1]}.$$

Lemma

Let w be a non-rational meromorphic solution of

$$P[z,w] = 0,$$

where P[z, w] is a differential-difference polynomial in w with rational coefficients and let $a_1(z), \ldots, a_k(z)$ be rational functions, satisfying $P[z, a_j] \not\equiv 0$ for $j = 1, \ldots, k$. If there exist s > 0 and $\tau \in (0, 1)$ such that

$$\sum_{j=1}^{k} n\left(r, \frac{1}{w - a_j}\right) \le k\tau n(r + s, w) + O(\log r),$$

then w has infinite order (in fact, the hyper-order of w is at least one).

Fast-growing solutions and singularity confinement

• Let w(z) be a non-rational meromorphic solution of

$$w(z+1) - w(z-1) = \frac{a(z)w'(z) + b(z)w(z)}{w(z)^2} + c(z),$$

where $a(z) \not\equiv 0$, b(z) and c(z) are rational.

• Suppose that w has a simple zero at $z = \hat{z}$,

$$w(z-1) = K + O(z - \hat{z}), K \in \mathbb{C},$$

$$w(z) = \alpha(z - \hat{z}) + O((z - \hat{z})^2), \alpha \in \mathbb{C} \setminus \{0\}$$

$$w(z+1) = \frac{a(z)}{\alpha(z - \hat{z})^2} + \frac{b(z)}{\alpha(z - \hat{z})} + c(z) + K + O(z - \hat{z}),$$

$$w(z+2) = c(z+1) + O(z - \hat{z}),$$

$$w(z+3) = \frac{a(z)}{\alpha(z - \hat{z})^2} + \frac{b(z)}{\alpha(z - \hat{z})} + O(1),$$

where there can be at most finitely many \hat{z} such that $c(\hat{z}+1)=0$.

• Assume now that $c(z) \equiv 0$:

$$w(z+1) - w(z-1) = \frac{a(z)w'(z) + b(z)w(z)}{w(z)^2} + c(z),$$

• Suppose again that w(z) has a pole at $z = \hat{z} + 1$, and that $w(\hat{z} - 1)$ is finite.

$$w(z-1) = K + O(z - \hat{z}), K \in \mathbb{C},$$

$$w(z) = \alpha(z - \hat{z}) + O((z - \hat{z})^2), \alpha \in \mathbb{C} \setminus \{0\}$$

$$w(z+1) = \frac{a(z)}{\alpha(z - \hat{z})^2} + \frac{b(z)}{\alpha(z - \hat{z})} + O(1),$$

$$w(z+2) = \alpha \left(1 - \frac{2a(z+1)}{a(z)}\right)(z - \hat{z}) + O((z - \hat{z})^2),$$

$$w(z+3) = \frac{a(z)(a(z+2) - 2a(z+1) + a(z))}{(a(z) - 2a(z+1))\alpha(z - \hat{z})^2} + \frac{\gamma(z)}{\alpha(z - \hat{z})} + O(1),$$

where

$$\gamma(z) = \frac{a(z)b(z+2) - (2a(z+1) - a(z))b(z)}{a(z) - 2a(z+1)} - \frac{2a(z+2)[a(z)a'(z+1) - a(z+1)a'(z)]}{(a(z) - 2a(z+1))^2}.$$

Delay alternating QRT

• Differential-difference mKdV (Ablowitz and Ladik):

$$\frac{\mathrm{d}w_n}{\mathrm{d}t} = \frac{1}{2}(1+w_n^2)\{(w_{n+2}+w_n)(1+w_{n+1}^2) - (w_n+w_{n-2})(1+w_{n-1}^2) - 2(w_{n+1}-w_{n-1})\}.$$

• Travelling wave reduction: $w_n(t) = u(z)$, where z = n - ct:

$$cu'(z) + \frac{1}{2}(1 + u(z)^2) \{ (u(z+2) + u(z))(1 + u(z+1)^2) - (u(z) + u(z-2))(1 + u(z-1)^2) - 2(u(z+1) - u(z-1)) \} = 0.$$

• When c = 0, this equation integrates to give

$$u(z+1) + u(z-1) = \frac{2u(z) + p(z)}{u(z)^2 + 1},$$

where p is an arbitrary period two function.

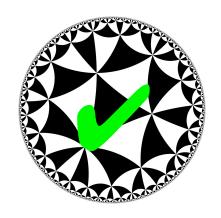
Summary

- Several delay Painlevé equations have been found.
- Such equations arise as symmetry reductions of integrable differential-difference equations.
- Others appear to arise as reductions of BTs for the Painlevé equations.
- The existence of finite order meromorphic solutions seems to be a reasonable characterisation of such equations.
- Some Lax pairs are known.

Complex Analysis video seminars (CAvid)

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