

$$\sum_{n=0}^{\infty} h_n t^n = \prod_{j=1}^{\infty} \frac{1}{1 - x_j t} \quad // H(t)$$

choose x_i and 1 everywhere else
"choose x_i 's but with repetition"

$$(1 + x_1 t + x_1^2 t^2 + \dots) (1 + x_2 t + x_2^2 t^2 + \dots) \dots$$

what is the coefficient of t ?

$$\Rightarrow \langle t^k \rangle p(t) = \text{coefficient in } t^k \text{ in } p(t)$$

$$\Rightarrow \langle t \rangle H(t) = x_1 + x_2 + x_3 + \dots = h_1$$

$$\langle t^2 \rangle H(t) = x_1^2 + x_2^2 + \dots + x_1 x_2 + x_1 x_3 + \dots = h_2$$

$$\begin{matrix} 1 + x_1 t + x_1^2 t^2 \\ 1 + x_2 t + x_2^2 t^2 \end{matrix}$$

Prop 2.3 (i) If $\lambda \notin \text{ex } \mu$, then $M_{\lambda \mu}(p, m) = 0$

$$(ii) M_{\lambda, \lambda}(p, m) > 0$$

$$\lambda = (\lambda_1, \lambda_2, \dots)$$

Proof: (i) $P_{\lambda} = \sum_{\mu \vdash |\lambda|} M_{\lambda \mu}(p, m) m_{\mu}$

$$\lambda = (2, 1) = \begin{matrix} \square & \square \\ \square \end{matrix}$$

$$\mu = (1, 3) = \begin{matrix} \square & \square & \square \end{matrix}$$

$$(x_1^2 + x_2^2 + \dots)(x_1 + x_2 + \dots) = Q_{\lambda}(X_{\infty})$$

$$\langle X^{\mu} \rangle Q_{\lambda}(X_{\infty}) = 0 \text{ if } \lambda \notin \text{ex } \mu$$

$$P_{\lambda} = (1) (x_1^2 + x_2^2 + \dots) \Rightarrow \lambda = \begin{matrix} \square & \square \\ \square \end{matrix}$$

$$\mu = \begin{matrix} \square & \square & \square \end{matrix}$$

$$\langle x_1 x_2 x_3 \rangle$$

$$(x_1^2 + x_2^2 + \dots)(x_1 + x_2 + \dots) \dots (x_1^{\lambda_i} + x_2^{\lambda_i} + \dots)$$

$x_i^{\mu_j}$
 $|\mu| = |\lambda|$
 $x_i^3 x_j$ or x_i^4

only get monomials $x_1^2 x_2$ or x_1^3

$$(x_1^3 + x_2^3 + \dots)(x_1 + x_2 + \dots)$$

$$x_i^4 \quad x_1^3 x_2 \quad x_i^4 \text{ or } x_i^3 x_j \quad i \neq j$$

$(x_1^{\lambda_1} + x_2^{\lambda_1} \dots) \dots (x_1^{\lambda_2})$

Constraints \leftarrow λ_1, λ_2

- At each point either tack on a different x_i from x_1
- or you add to $x_1 \leftarrow \Rightarrow \lambda_1 > \lambda_1$
- Repeat same analysis for x_2

(ii) - If you choose different x_i every time $\leftarrow \Rightarrow \lambda = \lambda$